



## **RULES GUIDE**

MAKEX CHALLENGE

Edited By MakeX Robotics Competition Committee





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## 1. Introduction

## 1.1 About MakeX

MakeX is an international robotics competition and education platform that promotes multidisciplinary learning within the fields of science and technology. It aims at building a world where STEAM education is highly appreciated and where young people are passionate about innovation by engaging them in exciting Robotics Competition, STEAM Carnival, Tech Event, Educational Conference etc.

As the core activity of MakeX, the namesake MakeX Robotics Competition provides exciting, challenging and high-level competitions in the spirit of creativity, teamwork, fun and sharing. It is committed to inspiring young people to learn Science (S), Technology (T), Engineering (E), Art (A) and Mathematics (M) and apply such knowledge in solving real-world problems.

## **1.2 MakeX Spirit**

**Creativity:** we advocate curiousness and innovation, encouraging all contestants to create unique high-tech works with their talent, and challenge themselves for continuous progress!

**Teamwork:** we advocate solidarity and friendship, encouraging all contestants to develop a sense of responsibility and enterprising spirit, and sincerely working with their partners for win-win development!

**Fun:** we encourage contestants to build a positive, healthy mindset in the competition. Enjoy the journey and grow in the process.

**Sharing:** we encourage contestants to have an open mind as a maker and share their knowledge, responsibility, and joy with everyone, including their teammates and competitors.

MakeX spirit is the cultural cornerstone of the MakeX Robotics Competition. We hope to provide a platform for all contestants, mentors and industry experts to exchange ideas, study and grow up, and help young people acquire new skills during creation, learn to respect others in teamwork, gain an enjoyable life experience in the competition, take delight in sharing with the society their knowledge and responsibility, and work hard to achieve their grand aspiration of changing the world and creating the future !

## **1.3 About MakeX Challenge**

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MakeX Challenge is a highly confrontational competition program for students between the age of 11-18.

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This program is very confrontational and enjoyable to watch, and the simple and easyto-understand rules enhance the overall experience of participation and engagement. The design and construction of bigger robots and programming can better improve the contestants' design abilities and multi-dimensional thinking abilities of advanced robots. Also, the contestants are exercising logical thinking, strategic analysis, communication and cooperation, and improving decision-making abilities in the competition.

# MAKEJ



## **2.**Competition Application

## **2.1 Participation Requirements**

**Participants:** Contestants shall participate in a team. The number of contestants is 2-8 for each team, with 1-2 mentor(s).

**Age:** Team members must be teenagers or children between the age of 11-18 (born between January 2, 2003 and December 31, 2011). The mentor must be at least 18 years old.

**Team Number:** The mentor will receive a team number after registration on MakeX official website.

**Team Roles:** Everyone in the team can play their respective roles as operator, observer, mechanist, programmer and so on. In each competition, one team can only appoint 1 operator and 1 observer to participate. Each alliance includes 2 operators and 2 observers, and one of whom is designated as the captain of the alliance. The operator is responsible for operating the robot, and the observer is responsible for assisting the operator in observing the status of props and making suggestions.

**Identification Symbols:** Each team must have a team logo, team name, and team slogan. Teams are encouraged to use uniforms, flags, posters, badges, base decorations, etc. to show the team culture.

## **2.2 Registration and Application**

Contestants and mentors that meet participation requirements can register on MakeX official website (www.makex.cc). After registration, mentors are able to form a team and sign up for a competition by using mentor's account.

If participating team wants to change their members before competition, which leads to inconsistency with the registration information, they should inform MakeX Robotics Competition Committee in advance to finish re-registration.

For more details about the registration and application, please refer to <u>MakeX</u> <u>Registration & Competition Application Guide</u>

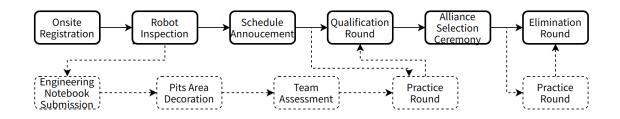
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## **3. Competition Procedure**

Participating teams shall pay close attention to related notices and program brochures published before each competition. If there are some updates in brochures, the latest rules will be adopted for the competition. MakeX Robotics Competition Committee reserves the rights and final interpretation to amend competition rules and system based on actual situation of different points race.

The schedule for each competition is determined by actual situation, and generally includes following procedures.



Note: The solid line frame refers to necessary procedure of each match, while the dotted line frame refers to non-essential procedure. The specifications of non-essential procedure can be understood based on Appendix 8 Supplementary Explanation of Competition Procedure. Please keep abreast of updates.

#### **Onsite Registration**

When a team arrives at the venue, mentors and contestants should show ID cards or other valid certificates (e.g. passport) for onsite registration and to get the competition pack. It is necessary for mentors to inform team members about the fire exit, match schedule, competition area, practice area and pits area, etc. Onsite registration and robot inspection will be conducted once the match schedule is generated.

#### **Robot Inspection**

The inspectors will strictly check the safety of robots on request. Teams can pre-check their robots and self-customized flag in advance based on "**Appendix 3 MakeX Challenge Energy Innovator Robot Self-Check List**". The robot and team flag will be inspected before the competition. If the inspection fails, the team needs to adjust their robots and check again until they pass the inspection. Those who fail to pass the inspection are not qualified for the competition.

#### Schedule Announcement



The committee will announce the match schedule at least 30 minutes before the competition starts through online official website and onsite announcement. The schedule includes match-up chart, match session and specific time, red alliance and blue alliance, etc.

#### **Qualification Round**

Normally, each team is requested to participate in four matches during qualification round. However, the session of qualification round may be different based on distinct points race. In qualification round, red alliance and blue alliance are automatically matched by the system. Points will be obtained by teams according to the winning or losing situation. It is conducted in the form of alliances confrontation and each team's alliance and the opponents will be allocated randomly by the system.

In each qualification round, team will receive corresponding points (including wins, ties, loss) regardless of competition type. Three points for a winner, one point for a tie, and no point for a loss. The final ranking is based on the sum of win-loss points and judging points, and the top-ranking teams will be promoted to the elimination round. If the team with the same ranking points, the ranking sequence will be determined according to following rules:

1) Team with higher win-loss points in the qualification round has a higher ranking.

2) If win-loss points are the same, team with higher total point differential in all qualification round has a higher ranking.

3) If above conditions are the same, team with highest total point in all qualification round has a higher ranking.

4) If above conditions are the same, team with highest point of a single round in all qualification round has a higher ranking.

5) If above conditions are the same, teams with the same ranking will play one-on-one extra match, and those who with the highest total point will be the winner.

#### **Alliance Selection Ceremony**

In alliance selection ceremony, promoted teams will select their alliance team in turn according to their ranking in qualification round. The alliance generated in this procedure will be the alliance team in elimination round, which will be named as Alliance One, Alliance Two, Alliance Three.... During this procedure, teams must abide by following rules (these rules only available for points race, other competitions must follow the rules unveiled before the competition).

When being chosen by other teams, promoted teams ranking top 50% can refuse for only once, and those teams ranking bottom 50% cannot refuse. If the team is refused

by another team, they can continue to choose another team until the alliance is formed.

The promoted teams who are not present before the start of alliance selection are deemed as voluntarily giving up the right to choose alliance, and those who are not present before the end of the alliance selection are considered to be as voluntarily quitting the elimination round. If the promoted teams quit amid the alliance selection ceremony, the promotion places will be given to the following teams according to the ranking in the qualification round.

The promotion proportion for 2022 season points race is as follows. However, the promotion quota in different competitions may vary according to actual situation.

Number of participating teams	Corresponding Number of promoted teams
121 or more	64
65-120	32
32-64	16
12-31	8

#### **Elimination Round**

In elimination round, the alliance generated in the alliance selection will be the opponent (red alliance and blue alliance are automatically matched by the system). The winner will be evaluated by BO3 (Best of 3) and the alliance who achieve "two wins" or "one win and two ties" can advance to next round until the champion, runner-up and second runner-up are elected.

If the alliance achieves " one win, one loss, one tie " or " three ties " in three rounds, the winning alliance will be decided according to the following rules:

1) If win-loss points are the same, team with higher total point differential in BO3 has a higher ranking.

2) If above conditions are the same, team with higher average points in BO3 has a higher ranking.

3) If above conditions are the same, team with highest point in BO3 has a higher ranking.

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4) If above conditions are the same, teams will play an extra match until the winner is elected.

Taking the promoted 32 teams as an example, the schedule of elimination round is as follows:





## **4.Competition Details**

The theme of the 2022 MakeX Challenge is "Energy Innovator".

Renewable energy is the key of future energy, an effective solution to the consumption of energy, and a ray of hope for sustainable human development. Renewable energy integrates human thought for production and consumption as well as innovation in technology development. By adopting supercomputers and cloud computing technology, energy innovation not only connects every port in the new energy industry chain, but also unites countless people who love this planet. Let's build a sustainable new energy planet together!

## **4.1 Introduction**

Each single match lasts for 4 minutes and 40 seconds.

MakeX Challenge Energy Innovator is a confrontational competition, among which red and blue alliance for each match, and two teams for each alliance.

Each match comprises four stages: automatic stage, manual stage, modification stage and final stage. In automatic and manual stages, contestants will control robots to finish following tasks: powering and collecting new energy pins (blue and red pins), computing and storaging alphabet cube (yellow cube) and other tasks. When the match ends, judges will calculate the points based on the final state. The alliance with the highest point will be the winner.

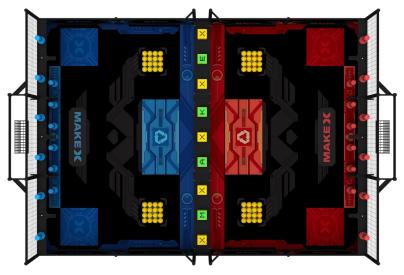


Fig 4.1 Top View of Competition Arena



### 4.2 Arena

The competition arena of MakeX Challenge Energy Innovator consists of map and frame. It is a rectangular area with the size of 2985 mm × 4185 mm and the outer frame's height is 400 mm. The arena mainly consists of starting area, renewable energy area, new energy data storage center (abbreviated as data storage center), energy recycling area, energy utilization station, new energy data collection center (abbreviated as data collection center), new energy data computing center (abbreviated as data computing center), flag hanging area.



#### Fig 4.2-1 Axonometric View of Arena

The central barrier evenly divides the arena into the red and blue camps, with data computing center located in the central area. Robots are only required to conduct corresponding tasks in their respective camp.

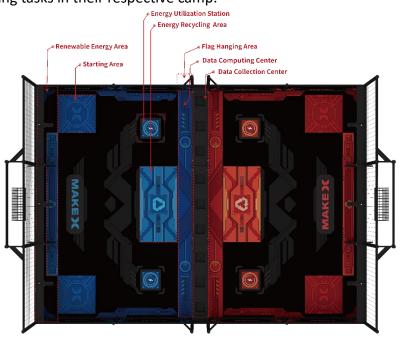


Fig 4.2-2 Top View of Arena

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**Data Collection Center** 



There is a data collection center (2985mm length x 200mm width) located at the junction of both sides (Fig 4.2-2). The height between the ground and data collection center is 254mm, while the height between the ground and the alphabet cube is 335mm (Fig 4.2-3). Nine alphabet cubes are available for both sides, which are placed in a regular sequence (Fig 4.2-4).

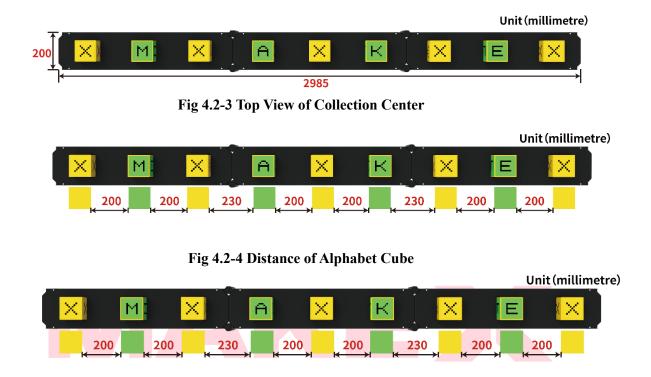


Fig 4.2-5 Front View of Data Collection Center

**Starting Area:** There are two starting areas in both camps, with the size of 500mm x500mm. Located in four corners of arena, this area is where robot be placed before automatic and final stage.

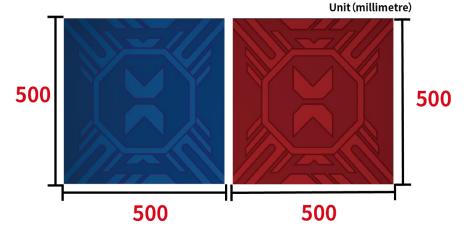


Fig 4.2-6 Starting Area

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There is a data computing center in both camps, with the size of 2985mm x 200mm. In this area, contestants can control the robots to place or pile up the cube to refrain the pins in energy recycling area and renewable energy area from being knocked down.

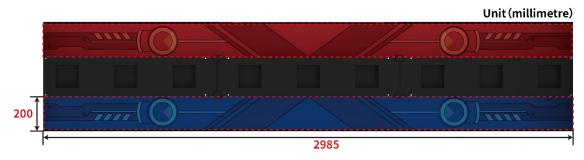


Fig 4.2-7 Data Computing Center

#### **Energy Recycling Area**

There is an energy recycling area in both camps, with the size of 500mm x 1000mm. Contestants can receive corresponding points when they control the robots to place the fallen renewable energy pins in this area.

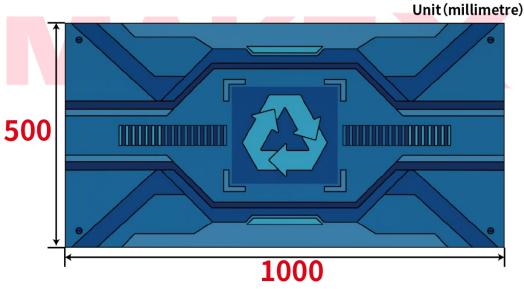
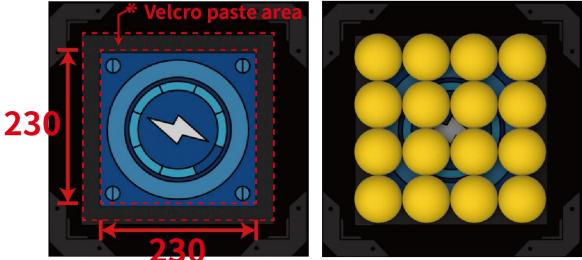


Fig 4.2-8 Top View of Energy Recycling Area



**Energy Utilization Station:** There are two energy utilization stations in both camps, with the size of 230mm x 230mm. The capacity of each energy utilization station is 16 energy powering ball with the diameter of 70 mm. Robots are allowed to collect energy powering ball in individual camp to knock down opponent's pins.

## **Unit (millimetre)**



#### Fig 4.2-9 Energy Utilization Area

#### Renewable Energy Area

There is a renewable energy area in both camps, which is divided in two layers. The size of upper layer is 110mm x 2895mm, while sublayer is 150mm x 885mm. The team can place 12 renewable energy pins in this area, and the location and number of these pins are decided by the captain of the alliance before the match.

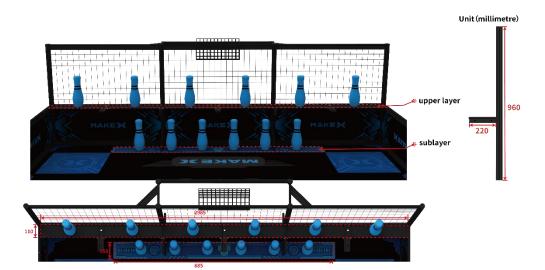


Fig 4.2-10 Renewable Energy Area

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#### **Data Storage Center**

There is a data storage center in both camps, which is made of octagonal pillars (960mm) and flat beams (220mm). The robot can insert the cube into the protrusion of flat beam. The cross-sectional size of the protrusion is 50mm x 15mm, which is arranged alternately in different directions.

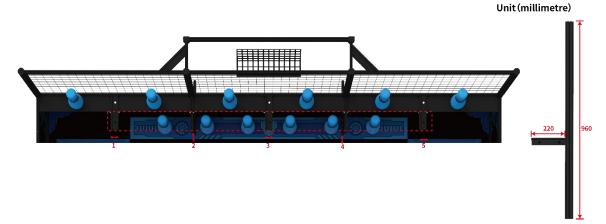


Fig 4.2-11 Data Storage Center

#### Flag Hanging Area

There are two symmetrical poles in both camps. The height between the pole and the ground is 960 mm, and the pole's lateral length is 160mm. The angle of the flat beam and the outer frame is 45 degrees, and the flat beam is for flag hanging.

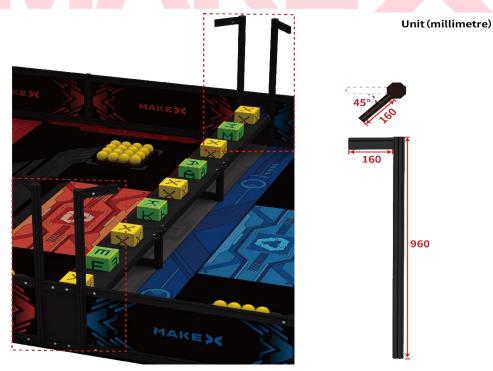


Fig 4.2-12 Flag Hanging Area

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## 4.3 Props

The initial position of the props before the match is shown in figure 4.3-1

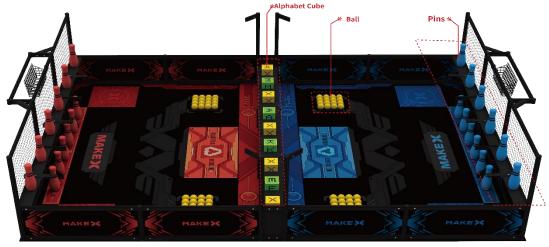


Fig 4.3-1 Initial Position of the Pros

#### **Energy Powering Ball**

Energy powering ball, a yellow one, is placed in energy utilization station, which is made of EVA and its size is 70mm. There are 16 balls being placed in each energy utilization station, with a total of 64 in the whole area. Robots are allowed to use the balls to shoot down the pins of opponent to complete the task of Renewable Energy Pin Powering.

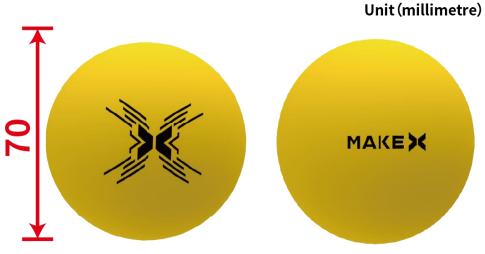


Fig 4.3-2 Energy Powering Ball

#### **Renewable Energy Pins**

Renewable energy pins refer to red and blue pins being placed in respective renewable

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#### **Energy Innovator**

energy area, which are made of EVA with a height of 290 mm. The diameter of the bottom of each pin is 70mm, and the maximum diameter is 100mm (Note: A tolerance of ±10mm is permitted).12 pins for half time and 24 pins for full time. It is available for



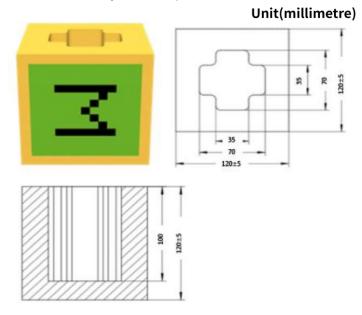


robots to toss the energy powering ball toward the pin.

Fig 4.3-3 Renewable Energy Pins

#### Alphabet Cube

Located in data collection station, alphabet cube is made of EVA with an edge length of 120 mm. There are 9 alphabet cubes with the bottom side having a hollow cross hole (fig 4.3-4), among which there are 4 alphabet cubes with a letter of [M], [A], [K], [E] respectively, and 5 cubes with a letter of [X]. During the match, the shared alphabet cubes can be used to complete the missions of Crambling, Computing and Storaging. (Note: A tolerance of ±5mm is permitted).





#### Fig 4.3-4 Alphabet Cube

\* Note: All arenas and props have certain and reasonable tolerances. If there are any objection to the size of the props or other problems, the captain of alliance can apply for replacement before the match, and the final decision is on referee.

## 4.4 Missions

The competition includes automatic stage, manual stage, modification stage and final stage. Task details of each stage are shown as follows:

Stage	Task Details	Operation Area
Automatic Stage (30 seconds)	Powering new energy pin, scrambling alphabet cube, calculating data cube,	Individual Camp
	storage alphabet cube.	
Manual Stage (100 seconds)	Adding the task of recycling renewable energy bottles to the executable tasks	Individual Camp
	in th <mark>e automatic stage.</mark>	
Modification Stage	Modificating individual robots.	Off-Site
(30 seconds)		
Final Stage (60 seconds)	Adding the task of flag hanging to the executable tasks in the manual stage.	Individual Camp

#### 4.4.1 Powering Renewable Energy Pins

**Operation Stage:** Automatic Stage, Manual Stage, Final Stage.

**Tasks Details:** Robots are allowed to collect yellow ball in the ground to toss opponent's pins.

#### Scoring State Judgement:

a. The pin of upper layer is vertical and its bottom is in complete contact with the upper renewable energy area (i. e., this area refers to renewable energy area).

b. The pin of ground layer is vertical and its bottom is in complete contact with the lower renewable energy area (i.e., this area refers to renewable energy area).

c. The pin has no direct contact with the robot.

Mission Points: All the above conditions are considered as valid scoring states. Twenty-



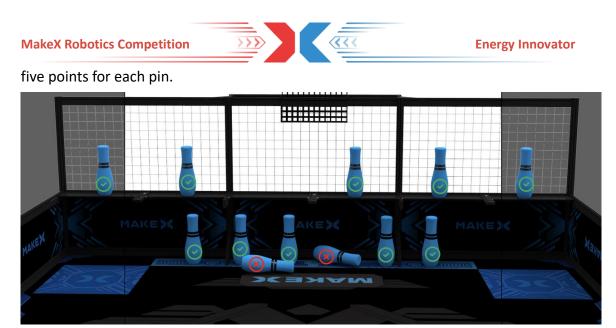


Fig 4.4-1 Valid and Invalid Scoring of Pins

#### 4.4.2 Recycling Renewable Energy Pins

**Operation Stage:** Manual Stage, Final Stage.

Task Details: Robots are allowed to place their pins in respective recycling areas.

**Scoring State Judgement:** It can be regarded as valid scoring state if the pin completely enters the recycling area and has no direct contact with the robot.

Mission Points: Twenty points for each pin.

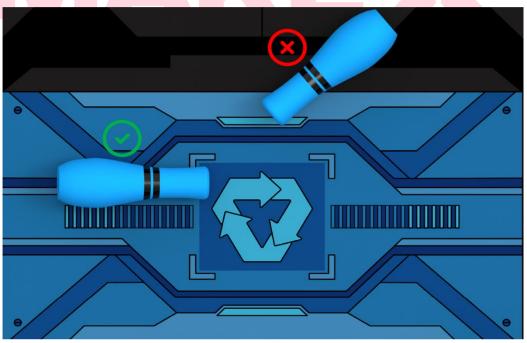


Fig 4.4-2 Valid and Invalid Scoring of Renewable Energy Pins



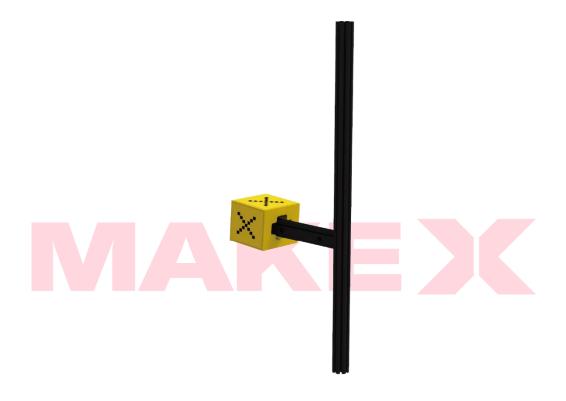
#### 4.4.3 Storaging Alphabet Cube

Operation Stage: Automatic Stage, Manual Stage, Final Stage.

Tasks Details: Robots are allowed to insert cubes into respective storage center.

**Scoring State Judgement:** The following situation is regarded as valid scoring state: the cube is suspended on the flat beam, and there is no direct contact with the robot or other arena elements (except the structural parts of the suspension area).

Mission Points: Thirty points for each cube.



#### Fig 4.4-3 Valid State of Storing Alphabet Cube

#### 4.4.4 Computing Alphabet Cube

**Operation Stage:** Automatic Stage, Manual Stage, Final Stage.

Tasks Details: Robots are allowed to place the cube in respective computing center.

**Scoring State Judgement:** The following situation is regarded as valid scoring state: the vertical projection of the cube completely falls in respective computing center, and there is no direct contact with the cube and the robot.

Mission Points: Fifteen points for each cube.



Fig 4.4-4 Valid and Invalid Scoring of Alphabet Cube in Computing Center

#### 4.4.5 Scrambling Alphabet Cube

**Operation Stage:** Automatic Stage, Manual Stage, Final Stage.

**Tasks Details:** Robots are allowed to collect the cube of collection station into individual camp.

**Scoring Statement Judgement:** The following situation is regarded as valid scoring state: the cube is completely in individual camp (as shown in fig. 4.5-5) and there is no direct contact between the cube and the robot.



Mission Points: Five points for each cube.

Fig 4.4-5 The Remaining Cube Except Those in Data Computing Center and Data Storage Center

#### 4.4.6 Hanging Team Flag

**Operation Stage:** Final Stage.

Tasks Details: Robots are allowed to hang the flag in respective flagpole of suspension area.

**Scoring Statement Judgement:** It can be regarded as valid hanging if the flag is hanging on the flagpole, and there is no direct contact with the ground and the robot.





Mission Points: Fifty points for one flag.



✓ Valid Point

Fig 4.4-6 Valid Scoring of Team Flag

### 4.4.7 MakeX Bonus

**Operation Stage:** Automatic Stage, Manual Stage, Final Stage.

**Tasks Details:** Robots are required to gather five alphabets of  $\lceil M \rfloor \lceil A \rfloor \lceil K \rfloor \lceil E \rfloor \lceil X \rfloor$  in respective camps.

Scoring Statement Judgement: It can be regarded as valid scoring if five alphabets of  $\lceil M \rfloor \lceil A \rfloor \lceil K \rfloor \lceil E \rfloor \lceil X \rfloor$  are gathered and located at any area of respective camp. (fig 4.5).

Mission Points: An extra 150 points for MakeX Bonus.



Fig 4.4-7 MakeX Bonus

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#### 4.4.8 Boundary State Judgement

During the match, if there is any uncertainty about the position of the robot (or props) and designated boundary, the following state judgement can be explained:



## 4.5 Scoring Explanation

The final score of the match is determined by the final static state of the scoring prop after the match. Competition tasks, scoring props and its corresponding points are as follows. After the competition, the referee calculates the sum of scores of each task, and the alliance with the highest score will be the winner.

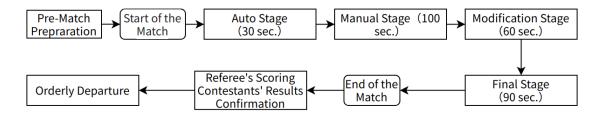
Single match Alliance points = Cube points + valid status pins + team flag - Penalty points

Scoring Props	Details of Scoring Props	Point of Single Prop	Maximum Point
Renewable Energy Pins	Valid Pin in Renewable Energy Area	25	300
	Valid Pin in Energy Recycling Area	20	
Alphabet Cube	Valid Cube in Data Storage Center	30	360
	Valid Cube in Data Computing Center	15	
	Valid Cube in individual Camp but Except for Cube in Data	5	
	Storage Center and Data Computing Area		
	Bonus Challenge: Gather Five	Bonus:150	



MakeX Robotics C	Competition >>>>	377	Energy Innovator
	Alphabets of 「M」「A」「K」「E」		
	「X」 in Individual Camp		
Team Flag	Valid Flag in Flag Hanging Area	50	100

## 4.6 Single Match Flow



#### **Pre-Match Preparation**

Before a single match, contestants are required to check the robot and the power management module in the inspection area. After the inspection, contestants should wait and enter the competition area under the guidance of staff.

#### Start of the Match

Contestants are not allowed to touch the robot until refree's instruction to start the competition.

#### Automatic Stage

The automatic stage lasts for 30 seconds.

To ensure the competition fairness, robots in the starting area are required to power off on the basis of competition system. After the countdown of automatic stage, the system will power on the robot and the robot can run the preset automatic program.

#### **Manual Stage**

The manual stage lasts for 100 seconds.

After the automatic stage ends, there is a preparation period before the manual stage begins. When referee announces the manual stage begins with a five-second countdown, the competition system will automatically power on the robots. In automatic stage, the operator can control the robot with bluetooth controller.

The competition system will have a five-second countdown at the end of automatic stage. In the meantime, the robot will be powered off and the competition will directly enters the modification stage.

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#### **Modification Stage**

The modification stage lasts for 60 seconds.



The modification stage begins after the end of automatic stage. Contestants are allowed to remove their robots (the vertical projections of the robots must partially or completely in the starting area.) out of arena and modify them. There are specifications for the length and width of the modified robot, and the height is not limited. (Please refer to 6.3 Modification Rules for the specifications.)

The competition system will give a signal when there is 30 seconds left. There will be ten-second countdown after the end of the modification stage. Before countdown, contestants should remove the robot to the starting area. If the robot fails to enter the starting area (partially in or completely in), the robot will be suspended in final stage.

#### **Final Stage**

The final stage lasts for 90 seconds.

After a five-second countdown, the system will power on the robot, and the operator can control the robot with blue-tooth controller. At the end of the final stage, the competition system will have a five-second countdown. The system will power off the robot after the end of countdown.

#### End of the Match

After the end of the match, the operator is required to place the blue-tooth controller in the storage basket and stay out of the arena.

#### Referee's Scoring and Contestants' Results Confirmation

The referee will count the scores after a single match. If there is no objection to the match, the captains of both alliances must confirm the match's result and sign on the Scoring Result Sheet. If there is any doubt about the result, the team can appeal to the referee without signing the result form.

After results confirmation, contestants shall actively assist the referee to restore the props, and leave the arena with their robots and blue-tooth controller in an orderly manner.



## **5.Technical Specifications**

## **5.1 Specification for Robot Construction**

The specification for robot construction provides a fair and safe competition standard for all teams and the committee encourages teams to make innovative designs of their robots on the prerequisites of meeting these specifications. The committee encourages teams to conduct hardware construction and software programming on the premise of observing the specifications. During the competition, it is a must for robots to abide by the specifications. Any robot that violates the specifications will be required to be modified. Those who commit serious offense will be punished for cancelling the results or disqualification.

#### **Robot Mechanical Specification**

**T01.** The size specification of the robot is: 500mm (length) x 500mm (width) x 700mm (height) before enhanced modification; 500mm (length) x 500mm (width), and with unlimited height after enhanced modification. The length and width of robot are defined before the competition, without redefinition after the competition. When measuring the robot size, the flexible material on it should not be affected by external forces. (The flexible material includes but not limited to rolled strip, tape, foam block, etc.).

	Requirements	Details	
Maximum Initial Size	500 mm (Length) 500 mm (Width) 700 mm (Height)	1.The height should not exceed 700 mm and the vertical projection of the robot on the arena should not exceed the square area of 500 x 500 mm.	
		2.Before the modification stage, the robot's size must comply with the requirement of maximum initial size.	
		3.The team should show the maximum size of the robot during the inspection.	
Maximum	500 mm(Length)	1.There is no limitation on height and the vertical	
Modified Size	500 mm(Width) Unlimited	projection of the robot on the arena should not exceed the rectangular area of 500 x 500 mm.	
	(Height)	2. After the modification stage, the robot's size	

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must comply with the requirement of the maximum modified size.
3. The team should show the maximum size of
the robot during the inspection.

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**T02.** The maximum net weight of the robot shall not exceed 10 kg, including the weight of battery, parts and flag.

**T03.** Robots must be equipped with connected structure rather than detached structure.

**T04.** The equipment with high performance that infringes the competition fairness is prohibited, which must be operated with following performance indicators:

| Equipment                | Component                       | Specification                                                                                                                                                                        | Note                                                                                                                                             |
|--------------------------|---------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------|
| Motor& DC Motor<br>Servo |                                 | 25 DC Motor<br>Rated Voltage: 6V<br>Rated Rotation Speed:<br>50&200RPM                                                                                                               | The maximum total<br>number of the motor<br>is 13.<br>The maximum total                                                                          |
|                          | Brushless<br>Motor              | 37 DC Motor<br>Rated Voltage: 12V<br>Rated Rotation Speed:<br>50&200RPM<br>2823/2824 Brushless Motor<br>Rated Voltage: 10000 mA MAX<br>Rated Rotation Speed: 7300                    | number of the smart<br>servo is 6.<br>It is forbidden to<br>change the mechanical<br>structure and<br>electrical layout of any<br>motor or servo |
|                          | Encoder<br>Motor<br>Smart Servo | rpm<br>180 Smart Encoder Motor<br>Rated Voltage: 12V<br>No-load Speed: 580±10%RPM<br>Reduction Ratio: 39:43<br>MS-12A Smart Servo<br>Working Voltage: DC6V~12.6V<br>Torque: 12kgf.cm |                                                                                                                                                  |

#### **T05.** The parts can be lubricated with lubricant, but contestants should protect the



#### arena from lubricant leaking.

**T06.** The following robot's parts that may cause danger are forbidden:

- Sharp angle;
- Oil pressure parts or hydraulic parts;
- Switches or contacts containing mercury;
- Parts that will conduct electrical current from robots to arena;
- Parts that tend to develop connections with other robots, such as hook-shaped parts and other parts;
- Other dangerous parts as determined by the judges.

**T07.** The following hazardous materials are forbidden:

- Flammable and explosive gases;
- Materials containing liquids or gelatinous substances (except for glues and lubricants used in prescribed and small quantities);
- Materials that may cause arena contamination, such as sand, ink, etc.;
- Materials made from animal tissue;
- Materials that may cause danger as determined by other judges.

**T08.** Each robot can only be equipped with one battery, and the battery must be fixed inside the robot except for laser sighting device. The battery is prohibited from colliding with and separating from the robot.

**T09.** The power of the laser sighting device should be less than or equal to 5mW (below Grade 3 a/R), and at most one laser sight

• Each robot is only allowed to install at most one laser sight.

**T10.** The battery cables shall be intact without cracks, breakages and metal wires. There must be an electrical isolation between power supply lines and robot structures.

**T11.** The electronic equipment with high-performance that infringes competition fairness is prohibited, which must be operated with following performance indicators:

| System              | Module        | Specification                                                         | Note                                            |
|---------------------|---------------|-----------------------------------------------------------------------|-------------------------------------------------|
| Power<br>System     | Li-Po Battery | 3S Li-Po Battery, Output Voltage<br>11.1-11.2v, Discharge Rate 25-30c |                                                 |
| Mainboard<br>System |               |                                                                       | Raspberry Pi 3<br>Model B+ is also<br>available |





| SystemEffective Focal Length: 4.65±5%<br>mmare not limited<br>It is forbidden for<br>robots to use any<br>sensors that will<br>interfere with the<br>perception ability<br>other robotsSystemBluetooth<br>ControlMethod of Power Supply: 3.7V<br>Lithium Battery or 5V mBuild<br>Power Consumption Range :<br>0.9-1.3WDuring the<br>competition, one<br>blue-tooth<br>Working Current: ≤25mA<br>Transmit Data: Data packets<br>within 100ms can be acquired by<br>blue-tooth devices (low latency)During the<br>control<br>to method<br>the blue-tooth<br>module should<br>competition, one<br>blue-tooth devices (low latency)                                                                                                                                                                                                                                          |        |               |                                                                                                                                  |                                       |
|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------|---------------|----------------------------------------------------------------------------------------------------------------------------------|---------------------------------------|
| SensorVision SensorViewing Angle: 65.0 degreesSystemVision SensorViewing Angle: 65.0 degreesSystemEffective Focal Length: 4.65±5%<br>mmType and quantity<br>are not limitedIdentification Speed: 60<br>frames/secondsIt is forbidden for<br>robots to use any<br>sensors that will<br>interfere with the<br>perception ability<br>other robotsWirelessBluetooth<br>ControlMethod of Power Supply: 3.7V<br>Lithium Battery or 5V mBuild<br>Power Consumption Range :<br>0.9-1.3WWirelessBluetooth<br>ControlBluetooth Version: Support 4.0+<br>Distance of Remission: 20m<br>Working Current: ≤25mA<br>Transmit Power: 4dBm<br>Transmit Data: Data packets<br>within 100ms can be acquired by<br>blue-tooth devices (low latency)During the<br>control should<br>ronoule should<br>ronoule should<br>ronoule should<br>ronoule should<br>ronoule should<br>ronoule should |        |               | minimum input voltage of motor is<br>required to meet the requirement<br>of motor's working voltage )<br>Communication Ports and |                                       |
| SystemEffective Focal Length: 4.65±5%<br>mmare not limited<br>It is forbidden for<br>robots to use any<br>sensors that will<br>interfere with the<br>perception ability<br>other robotsSystemIdentification Speed: 60<br>frames/seconds<br>Identification Distance: 0.25-1.2m<br>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |        |               |                                                                                                                                  |                                       |
| mmIt is forbidden for<br>robots to use any<br>sensors that will<br>interfere with the<br>perception ability<br>other robotsIdentification Distance:0.25-1.2m<br>is the best rangeinterfere with the<br>perception ability<br>other robotsMethod of Power Supply:3.7V<br>Lithium Battery or 5V mBuild<br>Power Consumption Range :<br>0.9-1.3WDuring the<br>competition, one<br>blue-tooth<br>controlWireless<br>SystemBluetooth<br>ControllerBluetooth Version: Support 4.0+<br>Distance of Remission:<br>20m<br>Working Current: ≤25mA<br>Transmit Power:<br>4dBm<br>Transmit Data:During the<br>competition, one<br>blue-tooth<br>controller is<br>available for one<br>team;<br>The blue-tooth<br>module should<br>rone<br>team;                                                                                                                                      |        | Vision Sensor |                                                                                                                                  | Type and quantity<br>are not limited  |
| Identification Speed: 00frames/secondsIdentification Distance: 0.25-1.2mis the best rangeMethod of Power Supply: 3.7VLithium Battery or 5V mBuildPower ModulePower Consumption Range :0.9-1.3WWirelessBluetoothControlSystemSystemBluetoothControlSystemDistance of Remission: 20mWorking Current: ≤25mATransmit Power: 4dBmTransmit Data: Data packetswithin 100ms can be acquired byblue-toothmodule shouldcontrol                                                                                                                                                                                                                                                                                                                                                                                                                                                     |        |               | -                                                                                                                                |                                       |
| Identification Distance: 0.25-1.2m<br>is the best rangeperception ability<br>other robotsMethod of Power Supply: 3.7V<br>Lithium Battery or 5V mBuild<br>                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                |        |               | -                                                                                                                                | sensors that will                     |
| Lithium Battery or 5V mBuild<br>Power ModulePower Consumption Range :<br>0.9-1.3WWireless<br>ControlBluetooth<br>ControllerBluetooth<br>ControlBluetooth Version: Support 4.0+<br>Distance of Remission: 20m<br>Working Current: ≤25mA<br>Transmit Power: 4dBm<br>Transmit Data: Data packets<br>within 100ms can be acquired by<br>blue-tooth devices (low latency)During the<br>competition, one<br>blue-tooth<br>controller is<br>available for one<br>team;                                                                                                                                                                                                                                                                                                                                                                                                          |        |               |                                                                                                                                  | perception ability of                 |
| O.9-1.3WWirelessBluetooth<br>ControlBluetooth Version: Support 4.0+<br>Distance of Remission: 20m<br>Working Current: ≤25mA<br>Transmit Power: 4dBm<br>Transmit Data: Data packets<br>within 100ms can be acquired by<br>blue-tooth devices (low latency)During the<br>competition, one<br>blue-tooth<br>controller is<br>available for one<br>team;                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |        |               | Lithium Battery or 5V mBuild                                                                                                     |                                       |
| Wireless<br>ControlBluetooth<br>ControlBluetooth Version: Support 4.0+<br>Distance of Remission: 20m<br>Working Current: ≤25mA<br>Transmit Power: 4dBm<br>Transmit Data: Data packets<br>within 100ms can be acquired by<br>blue-tooth devices (low latency)During the<br>competition, one<br>blue-tooth<br>controller is<br>available for one<br>team;                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |               |                                                                                                                                  |                                       |
| Control<br>SystemControllerDistance of Remission: 20mcompetition, one<br>blue-tooth<br>controller is<br>available for one<br>team;Controller<br>SystemDistance of Remission: 20mblue-tooth<br>controller is<br>available for one<br>team;Transmit Data:<br>blue-tooth devices (low latency)The blue-tooth<br>module should<br>connoct with New                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |        |               |                                                                                                                                  |                                       |
| System<br>System<br>System<br>System<br>Distance of Remission: 20m<br>Working Current: ≤25mA<br>Transmit Power: 4dBm<br>Transmit Data: Data packets<br>within 100ms can be acquired by<br>blue-tooth<br>team;<br>The blue-tooth<br>module should<br>connoct with Nov                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                     |        |               | Bluetooth Version: Support 4.0+                                                                                                  | -                                     |
| Working Current: ≤25mA<br>Transmit Power: 4dBm<br>Transmit Data: Data packets<br>within 100ms can be acquired by<br>blue-tooth devices (low latency)<br>with Nove<br>blue-tooth devices (low latency)                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |        | Controller    | Distance of Remission: 20m                                                                                                       |                                       |
| Transmit Data: Data packets team;<br>within 100ms can be acquired by The blue-tooth<br>blue-tooth devices (low latency) module should                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    | System |               | Working Current: ≤25mA                                                                                                           |                                       |
| within 100ms can be acquired by The blue-tooth<br>blue-tooth devices (low latency) module should                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |        |               | Transmit Power: 4dBm                                                                                                             | available for one                     |
| blue-tooth devices (low latency) module should                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |        |               | Transmit Data: Data packets                                                                                                      | team;                                 |
| connect with New                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                         |        |               | within 100ms can be acquired by                                                                                                  | The blue-tooth                        |
| Battery, Two No 5 AA Dry connect with Nova                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                               |        |               | blue-tooth devices (low latency)                                                                                                 |                                       |
| Batteries Pi mainboard                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |        |               | Battery: Two No.5 AA Dry<br>Batteries                                                                                            |                                       |
| Supported Platform: macOS /<br>Windows                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                   |        |               |                                                                                                                                  |                                       |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |        |               | Bluetooth Version: BT4.0                                                                                                         | It is forbidden to use                |
|                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                          |        | Module        | Band Range: 2402~2480MHz                                                                                                         | any form of wireless                  |
| Antenna Gain: 1.5dBi communicate with                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                    |        |               | Antenna Gain: 1.5dBi                                                                                                             | control device to<br>communicate with |
| Energy Consumption Grade: robots other than<br>≤4dBm the official blue-                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  |        |               | •••                                                                                                                              | robots other than                     |
| Working Current: 15mA tooth controller,<br>including but not<br>limited to any                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                           |        |               | Working Current: 15mA                                                                                                            | including but not                     |

| MakeX Robotics Competition | Energy Innovator       |
|----------------------------|------------------------|
|                            | artificially triggered |
|                            | sensors                |
|                            |                        |
|                            |                        |
|                            |                        |
|                            |                        |
|                            |                        |
|                            |                        |

**T12.** Except for the buzzer embedded in motor and main board, robots are not allowed to equip with any other electrical sound equipment. In the meantime, robots shall not be equipped with other lighting devices except for the mainboard, the sensor indicator light, the light used with the sensor and the laser sighting device that meet the technical specifications.

**T13.** Teams are allowed to self-construct or procure mechanical parts. It is suggested to use complete commercial product components with low integration, such as hinges, sprockets, roller chains and pulleys, etc. It is not allowed to use highly integrated complete commercial products, including but not limited to multi-DOF manipulators or mechanical hand.

## **5.2 Specification for Team Flag**

**T14.** The flag consists of flag surface and flagpole, which are made of flexible materials. The flag must be unfolded during the competition and its size is no less than 400 mm (length) x 300mm (width).

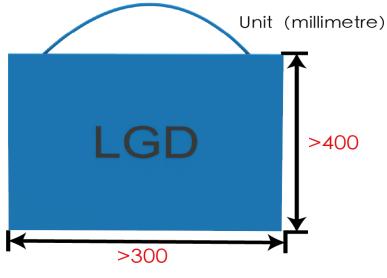


Fig. The Size of Flag

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• The flag surface and flagpole should not in contact with the ground, and do not lean on anything except for Cylinder and Max.

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- Flag can be carried to the competition arena after robot inspection and pre-match inspection.
- At most one flag for per team.
- The committee encourages teams to draw personalized patterns or words on the flag, which calls for positive content reflecting competition theme and spirit, without showing words or pictures related to MakeX Robotics Competition Committee.

# MAKEJ



## **6.Competition Rules**

## 6.1 Penalty

Verbal Warning

**E01.** The referee gives the team a verbal warning of the first violation and asked them to stop any violation and obey the referee's instructions. In the meantime, no points will be deducted and the competition will not pause.

#### Violation

**E02.** The referee issues a violation to the team, and immediately deducted 20 points. In the meantime, the competition will not pause.

#### Suspension

**E03.** The referee issues a suspension to ask the robot to stop its action. The Referee is entitled to suspend robots according to the actual situation in the Arena.

• The contestants shall ask the referee to suspend the robot while encountering robot malfunction or uncontrollability.

#### Yellow card

**E04.** If alliance members' behavior seriously affects the competition fairness or violates the safety rules, the alliance will receive a yellow card with 60 points deductions.

**Accumulation of yellow card:** In Qualification Round, the accumulation of Yellow Card for each match is counted for one team. If one team receives two Yellow Cards, it will be escalated to a Red Card. In the Elimination Tournament, the accumulation of Yellow Card for each match is counted for one Alliance. If one Alliance receives two Yellow Cards, it will escalate to a Red Card, will be cleared after qualification round.

• If a team receives a yellow card, 60 points deductions from its alliance.

#### **Red Card**

**E05.** If alliance members' behavior seriously affects the competition fairness or violates the safety rules, the alliance will receive 120 points deductions, and its robot will be suspended. If a team receives a red card in automatic stage, its robot must be taken out from arena after the end of automatic stage.

#### Penalty of Red Card:

**Qualification Round:** When the contestant's or related person's action that extremely affect the fairness of the competition or violates the safety principle, the Alliance will

receive a Red Card with 120 points deductions for both Alliance teams. The robot will be suspended, but the match will continue as usual. If two teams of the alliance receive a red card, the alliance will be the loser. (The winner will receive extra 10 points higher than the final score of the loser)

**Elimination Round:** If the alliance receives a red card, the alliance will be the loser. (The winner will receive extra 10 points higher than the final score of the loser)

#### Disqualification

**E06.** If the team receives disqualification by the referee, its robot will be immediately suspended, and the team will lose the chance to participate in this match and next match. If two teams from the same alliance are disqualified, the alliance will be the loser with zero point, while another alliance will be the winner with current score as their final score.

#### **6.2 Operation Rules**

#### **Dangerous Structure**

**R01.** The measure of safety protection should be taken if robot's structure may cause damage to humans, such as sharp angles.

• The contestants must modify the robot after receiving verbal warning, otherwise the robot will be suspended.

Destructing or Contaminating Arena

**R02.** Robots are not allowed to maliciously "climb" or "collide" the boundary of the arena and the central partition.

• The robot that violates the rules will be suspended from the match. A second violation will lead to disqualification.

**R03.** If arena contamination caused by the robot, the robot will be regarded as in an unsafe state. Robots are not allowed to use double-sided tape or glue to fix arena elements during competition.

The robot that violates the rules will be suspended from the match. If the robot continues to be a participant, contestant should modify it to accept re-inspection. A second violation will be disqualified.

#### **Destructing Other Robots**

**R04.** Robots are not allowed to collide with other robots during competition.

• The robot that violates the rules will be suspended from the match. A second violation will lead to disqualification.



#### **Robots Out of Boundary**

**R05.** Any parts of robot are not allowed to go beyond the arena boundary.

If robot is in contact with the ground and the object, the robot will be suspended and those who commit a second offense will be disqualified.

Violating Materials.

**R06.** The following hazardous materials or dangerous structures embedded in robot are forbidden, such as:

- Flammable gases, fire or smoke generating equipment, hydraulic oil or hydraulic parts, switches or contacts containing liquid mercury (mercury);
- Hazardous Substances (e.g., Lead);
- Materials that may cause arena contamination, such as sand and other objects that may be scattered during competition;
- Materials that develop connections with other robots;
- Materials with sharp edges that may cause injury.
- Materials made from animal tissue (for health and legal consideration).
- Materials containing liquids or gelatinous substances (except for glues and lubricants).
- Parts that can conduct electrical current from robots to any other parts in arena.
- The robot that violates the rules will be suspended. If the robot continues to be a participant, contestant should modify it to accept re-inspection. A second violation will be disqualified.

#### **Other Unsafe Factors**

**R07.** In addition to R06, referees are entitled to decide whether the robot is safe or not.

• The robot that violates the rules will be suspended. The robot needs to be modified and inspected before it can be back to the match. Repeated against this rule twice will result in disqualification.

#### Team Role

**R08.** One operator and one observer for each team. Each alliance includes two operators and two observers, one of them is selected to be the captain of the alliance.

- Operators are responsible for controlling the robot in each match.
- The operator and the observer can freely switch their roles during the match.





# Contestants' Requirements

**R09.** Contestants should wear goggles during competition preparation,

robot debugging and on-field match.

**R10.** Contestants should tie up their long hair during competition preparation, robot debugging and on-field match. Toe-baring shoes are forbidden.

# **Contestants' Standing Position**

**R11.** Contestants shall stand in certain range as shown in the following figure (the size of the operating area is subject to actual conditions):

• The team will receive a verbal warning, and those who commit a second offense will receive a violation.

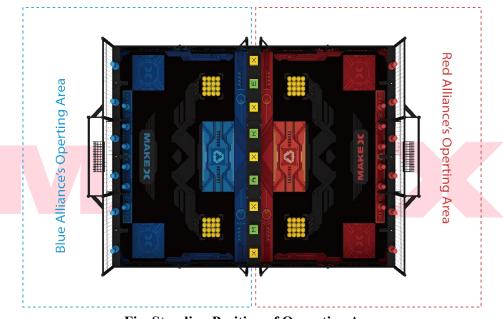


Fig. Standing Position of Operating Area

# Substitution of On-Arena Players

**R12.** It is not allowed for a third person as a substitution of operator and observer.

The team will receive a red card.

# **Rules of Elimination Round**

**R13.** After the end of each elimination round, each alliance has 5 minutes for debugging.

• The team will receive a verbal warning, and those who commit a second offense will receive a violation.





#### **Radio Interference**

**R14.** It is not allowed for contestants to bring electronic communication devices (mobile phone, transceiver, computer, wireless network devices and etc) into the competition area except for prescribed devices.

• The team will receive a violation, and those who commit a second offense will receive a yellow card.

# **Operating the Robot in Advance**

**R15.** Robots are not allowed to operate until referee's announcement to start the competition.

• The team will receive a violation, and those who commit a second offense will receive a yellow card.

# Delayed end of the Competition

**R16.** After the end of automatic stage, manual stage and final stage, operator should stop controlling the robot or stop robot's operation program (except for the motion caused by inertia).

• The team will receive a violation. An invalid point will be given to those offenders who enjoy the advantage as a result of delayed end of competition. Besides, the offender is required to reset the original state of the arena.

# **Violating Contact**

**R17.** Except for the Modification Stage, the contestants should not touch arena elements such as the scoring props, the arena's frame and the robots etc. during the match, including but not limited to the cases where the operator leans on the fence and the contestants push the robot. In case the Direct Contacts occur outside the arena due to the normal movement of small cubes or other props, they are not bound by this rule.

• The team will receive a violation, and those who commit a second offense will receive a yellow card.

# **Physical Interference**

**R18.** In order to ensure an unblocked attacking router for opponent, team members should keep their body projection out of the arena during the competition. This rule is exception to the action of moving robots in and out of the arena during the modification stage.

• The team will receive a violation, and those who commit a second offense will receive a yellow card.



# Using Bluetooth Controller in Automatic Stage

**R19.** Bluetooth controller should be connected with robot before the match, and the former one needs to be switched on. It is not allowed to use blue-tooth controller in automatic stage, otherwise the referee has the right to give the team a disqualification.

The team will receive a red card.

# **Operating Suspended Robot**

**R20.** When the robot is suspended, the operation teams cannot continue to control it.

• The team will receive a Violation for the first time. In case a serious situation will receive a Yellow Card. Depending on how serious of the situation the team may receive disqualification.

# **Robot's Left-Behind Components**

**R21.** During the competition, the following situation is forbidden, such as detachment of robot and its component and left-behind mechanical devices (detachment refers to detachment of robot ontology and its components). This rule is exception to the shedding caused by collision of opponent's robot or direct contact with other robots.

• The team will receive a violation in case it affects the progress of the competition. A second offense will be given a yellow card.

# Robot Inconformity

**R22.** Robots must comply with the size, weight and other parameters specifications during the match. Except that the robot size exceeds the requirements caused by opponent's toss of arena elements.

• The team will receive a red card.

# **Toss in Violation**

**R23.** Robots are not allowed to toss arena elements to opponent's camp. (such as the toss of pins, robot parts, alphabet cubes or blank cube)

• The team will receive a yellow card. The arena elements need to be restored if it causes any changes of arena elements in the opponent's side.

# **Completely in Opponent's Camp**

**R24.** During the competition, the robot shall not enter the opponent's area completely through the hollow part of the partition at the bottom of the midfield.

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• The team will receive a yellow card.

# Restricting the Movement of Opponent's Robot

**R25.** Robots are not allowed to prevent the robot of other alliance from moving in all directions or touching arena elements.

• The team will receive a violation, and those who commit serious offense will receive a yellow card.

**R26.** As part of robot's ontology enters opponent's camp, which leads to the other side's alliance robot being stopped or restricted, the competition will be suspended based on actual situation, and robots of both alliances must be detached as soon as possible.

• The team will receive a violation, and those who commit serious offense will receive a yellow card.

## **Mentoring in Violation**

**R27.** During the competition, contestants other than family members and mentors are allowed to enter the competition area. In case of mentoring in violation, the referee is entitled to give the team a disqualification.

 The team will receive a verbal warning, and those who will receive a violation if they refuse to correct their mistake. Those who will be disqualified based on actual situation.

#### **Off-Arena Contact**

**R28.** During the competition, contestants are not allowed to have any direct contact with off-arena person and audiences, including but not limited to the delivery of the parts and blue-tooth controller.

• A second violation will receive a violation.

# **6.3 Modification Rules**

In terms of those behavior that seriously violate the medication rules, the committee is entitled to give the team a disqualification.

The Robot Not in the Starting Area Before Modification Stage

**R30.** At the end of the Manual Stage, the robot needs to be taken out from the

Starting Area for modifications. In case the robot is not inside the Starting Area

(Partially or Completely In), it will not be allowed to conduct any operations during

the Modification Stage.

• The team who modifies the robot that is not inside the Starting Area will receive a red card.



## Modify Outside the Designated Area

**R31.** The team can only modify the robot after the vertical projection of the robot is completely outside the Arena. Modification cannot be conducted when the robot is lifted just above the Arena.

• Team who is against this rule will receive a Violation.

Changing the State of Arena Elements

**R32.** Contestants are not allowed to change the state of arena elements on purpose or touch the scoring props (such as robots but except for small yellow cubes) when they are taking out the robot.

 The team will receive a violation. An invalid point will be given to those offenders who enjoy the advantage as a result of changing the state of arena elements.
Besides, the offender is required to reset the original state of the arena.

# The Robot Not Inside the Starting Area After Modification Stage

**R33.** The robot should be placed in their own Starting Area before the end of the Modification Stage.

• The robot who is against this rule will be suspended.

# **Robot's Requirements after Modification**

**R34.** The robot after the Modification Stage should conform with the modification state at the time of inspection, including but not limited to the Maximum Modification Size. (The height of Robot is not limited.)

• The team who against the rule will receive a Red Card.



# 7. Appeal and Arbitration

# 7.1 Results Confirmation

# **Results Confirmation**

When a single match ends, captains of both teams need to confirm the results with the referees and then sign the result form. Both teams shall not have any objection to the results of this single match after their signatures.

# **Dispute Settlement**

If the team has any objections to the results and referee's explanation, they can refuse to sign the score sheet. Instead, they need to write clearly about the situation on the remarks part of the result form.

# 7.2 Appeal Procedure and Valid Appeal Period

# **Appeal Procedure**

Appeals should be lodged within the "valid appeal period" by the prescribed procedure and follow the civil participation spirit. The captain of the team needs to fill in the Appeal Form, then cooperates with the Arbitration Commission to investigate actual situation. Both sides will be required to arrive at the designated place if the Arbitration Commission requires. During the investigation, the captain of the appeal team must be present, and only captains or contestants of both teams can be present. The Arbitration Commission has the right to communicate with the the team alone, avoiding the mentor, the parents of the contestants, their relatives, or friends. The appellant should express facts clearly and objectively, not being over-emotionally.

# Valid Appeal Period

Normally, the appeal should be lodged within 30 minutes after the end of the competition. Please check the Program Brochure for a specific effective appeal period before the competition. The appellant and the respondent must be present at the designated place on time.

# **Appeal Response**

Normally, the Arbitration Commission responds to the appeal after the end of the competition on the same day or before the start of the competition on the next day.

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# 7.3 Invalid Appeal

# **Overdue Appeal**

Appeals that are not lodged within the "valid appeal period" will be considered invalid and inadmissible. If the appellant fails to be present on time or leaves without any reason during the investigation, the appeal will be considered invalid. If the respondent fails to be present on time, the Arbitration Commission will directly determine the arbitration result and render it as a final result.

# **Appellants out of Stipulation**

The appellants must be the participating contestant and the appeal of another person is inadmissible. The Arbitration Committee will caution the offending team if parents, mentors, or other persons out of the stipulation participate in the arbitration process without the permission of the Arbitration Committee.

A disqualification will be given for multiple invalid warnings.

# Vague Appeal's Requests

If the Arbitration Commission is unable to understand the appeal or conduct the normal investigation due to emotion factor of the appealing party, the offending party will receive a verbal warning.

A disqualification will be given for multiple invalid warnings.

# **Uncivil Appeal**

Neither side shall make uncivil behavior nor offensive action and remarks.

A disqualification will be given for multiple invalid warnings.

# 7.4 Arbitration Procedure

# **Arbitration Procedure**

The Arbitration Commission consists of the chief referee, the arbitration consultant, and the competition technical director. The Arbitration Commission is responsible for accepting the appeals and conducting arbitration investigations, to ensure the smooth progress of the competition and the fairness and justice of the competition results. The playback videos and photographs of any competition may be inaccurate due to the shooting angle, which is only used as reference but not arbitration evidence.

# **Arbitration Results**

The arbitration results can be divided into "maintaining the original result of the match" or "re-match", and the two teams shall not appeal again. If the arbitration result is a



"re-match", the two teams shall have a re-match according to the time and arena stipulated in the Appeal Form. If either team fails to reach the arena within 5 minutes after the beginning of the match, the team shall be deemed to quit the match.

# **Additional Remarks**

The Arbitration Commission determines the final arbitration result, and neither side shall dispute the result of the appeal anymore.

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# 8.Statement

MakeX Robotics Competition Committee reserves the final interpretation of 2022 MakeX Challenge Energy Innovator Rules Guide.

# **8.1 Rules Explanation**

In order to ensure a fair competition and high-quality competition experience, MakeX Robotics Competition Committee has the right to update and complement this Rules Guide regularly, issue and implement the latest version before the competition.

During the competition, all matters not stated in the Rules Guide shall be decided by the referee team.

This Rules Guide is the basis for refereeing, and the referee team has the right of adjudication during the competition.

# 8.2 Disclaimer

All contestants in 2022 MakeX Robotics Competition shall fully understand that safety is the most important issue for the sustainable development of the MakeX Robotics Competition. To protect the rights and interests of all contestants and organizers, according to relevant laws and regulations, all contestants registered for the 2022 MakeX Challenge Energy Innovator, shall acknowledge and abide by the following safety provisions:

Contestants shall take adequate safety precautions when constructing the robots, and all parts used for constructing the robots shall be purchased from legal manufacturers.

Contestants shall ensure that the structural design of the robots takes into account the convenience of the inspection and actively cooperate with the host of the competition.

When modifying and using the parts with potential safety hazards for the robots, it must conform to the national laws, regulations, and quality & safety standards. Those operations shall be manufactured and operated by persons with relevant professional qualifications.

During the competition, the teams shall ensure that all the actions such as construction, testing, and preparation will not do harm to their team and other teams, referees, staff, audiences, equipment, and arenas.

In the process of construction and competition, if any action that may violate the national laws, regulations, or standards occur, all consequences will be borne by the



contestants themselves.

The competition kits and parts sold and provided by the supporter, MakeX Robotics Competition Committee, shall be used by the instructions. MakeX Robotics Competition Committee will not be responsible for any injury or loss of property caused by improper use.

The official language for MakeX is Chinese. English or other language translations are prepared to facilitate the team's preparation process. All documents translated to English are for reference only.

# **8.3 Copyright Declaration**

MakeX Robotics Competition Committee reserves the copyright of this Rules Guide. Without the written consent or authorization from MakeX Robotics Competition Committee, any entity or individual may not reproduce, including but not limited to any network media, electronic media or written media.

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# **Appendix 1. Awards and Annual Points**

In 2022 season, MakeX Explorer competition shares the same rules of annual points as MakeX Challenge competition. According to competition scale and team number, the competition will be classified into Points Race/Regional Competition, National Competition, Intercontinental Competition, and World Championship. In MakeX Challenge Energy Innovator competition, teams can obtain the points based on the number of wins, ties and losses in the match. Each team can voluntarily sign up for all kinds of Points Race all year round to accumulate the annual points. The accumulation of annual points is based on the Team Number.

In single points race, teams can obtain annual points based on the winning points in qualification round and elimination round.

| Competition Type                | Rounds                  | Win | Tie | Loss |
|---------------------------------|-------------------------|-----|-----|------|
| Points Race Regional            | Qualification           | 5   | 2   | 1    |
| Competition                     | Elimination (Best of 3) | 10  | /   | 2    |
|                                 | Qualification           | 10  | 4   | 2    |
| National Competition            | Elimination (Best of 3) | 20  | /   | 4    |
|                                 | Qualification           | 15  | 6   | 3    |
| Intercontinental<br>Competition | Elimination (Best of 3) | 30  | /   | 6    |

Teams that have won the champion, runner-up, second runner-up and other awards can obtain additional annual points. For the details of award list, please refer to **2022** MakeX Awards Guide.

| Category              | Awards            | Regional<br>/Points Race | National | Intercontinental |
|-----------------------|-------------------|--------------------------|----------|------------------|
|                       | Champion          | 15                       | 30       | 45               |
| Explorer              | Runner-up         | 10                       | 20       | 30               |
| Challenge<br>&Premier | Second runner-up  | 5                        | 10       | 15               |
|                       | Innovative Design | -                        | 5        | 10               |

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|-----------------------------------------------------|-------------------------------|---|---|----|--|--|--|
|                                                     | Award                         |   |   |    |  |  |  |
|                                                     | Engineering<br>Notebook Award | - | 5 | 10 |  |  |  |
|                                                     | Outstanding Mentor<br>Award   | - | - | -  |  |  |  |
| Excellence                                          | Promotion<br>Ambassador Award | - | 5 | 10 |  |  |  |
| Award                                               | Technology Sharing<br>Award   | - | 5 | 10 |  |  |  |
|                                                     | MakeX Spirit Award            | - | - | 10 |  |  |  |

For example, team X20000 obtains the champion in one Points Race, and all the results show as below.

| Qualification Qualification |                               | Qualification | Qualification                | Annual Points             |
|-----------------------------|-------------------------------|---------------|------------------------------|---------------------------|
| Round 1                     | Round 2                       | Round 3       | Round 4                      | from                      |
| Win (5)                     | Loss (1)                      | Tie (2)       | Win (5)                      | Qualification<br>Round=13 |
| Top Eight Battle            | Eight Battle Semi-final Final |               | nal                          | Annual Points             |
| Win (10) Win (10)           |                               | Win           | from Elimination<br>Round=30 |                           |

The total annual points that team X20000 obtains = 13+30+15 = 58.



# **Appendix 2. Engineering Notebook Guideline**

# 2022 MakeX Robotics Competition

# **Engineering Notebook Guideline**

## \*Instruction:

**1. The value of engineering notebook**: It helps the team establish files and record the whole learning process. Therefore, it is necessary to record engineering notebook during the entire preparation for the competition.

**2.Engineering notebook submission**: Teams can use online documents or handwriting. No matter which way to use, each team must submit a paper version onsite.

Paper engineering notebook: As the Challenge & Premier programs require the assessment process, 1 copy of the paper version shall be submitted by each team to the judges onsite. If there is no assessment process (Starter & Explorer), each team will need to submit 1 copy of the paper version to the staff at the inspection area. Teams that cannot submit the original engineering notebook should prepare their own copies.

3. An engineering notebook will be required for the evaluation of all technical awards. Please refer to the Competition Guide for the evaluation criteria.

# **Basic Requirements for Cover**

The team's name, team number, and competition program must appear on the cover of the engineering notebook.

# **Basic Requirements for Contents**

# 1. Clear content

Creating content brings convenience for the judges to review and quickly find the corresponding section.

# 2. Process records (Required)

Every improvement of the robots should be recorded from prototype design, construction, to the debugging. **Keep pictures of all manuscripts, design drawings,** 



#### calculation processes, circuit diagrams, etc., and insert them into the engineering

## notebook in the form of pictures.

- 1) Schedule of robot building progress
- 2) Design inspiration/sketch
- 3) Technical principle (it can be disassembled into different parts)
- 4) Production step by step (with clear pictures)
- 5) Problems encountered and solutions

Examples of problems:

What technical failures did you encounter? Why did you fail? How did you solve the

problems finally?

What efforts have you made for the robots? What improvements have been

achieved?

Does your project progress schedule go as planned? What accidents or delays have occurred? How to fix it?

Have there been any disputes among the team members and how to settle them in the end?

# 3. Projects summary

- 1) The structure and function of the project (with pictures and text enclosed)
- 2) The technical innovations of the project
- 3) Competition strategies for scoring and defenses

# 4. Team introduction

- 1) A brief biography of each team member and their role on the team
- 2) Culture displaying (logo, team flag, slogan, posters, T-shirt, etc.)
- 3) Excellent achievements sharing (Stories)

# 5. Feelings and other things you want to share (optional)

- 1) Achievement in the competition (Technical)
- 2) Growth in the competition (Spiritual)
- 3) Suggestions for competition

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# Appendix 3 MakeX Challenge Robot Self-Check List

|    | MakeX Challenge Robot Self-Check List (Energy Innovator) |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |    |  |  |  |  |  |  |
|----|----------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----|--|--|--|--|--|--|
|    | Size and Weight of Robots                                |                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                        |    |  |  |  |  |  |  |
| SN | Items                                                    | Specific Requirements                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                  | 状态 |  |  |  |  |  |  |
| 1  | Size                                                     | The initial size refers to the size of the robot<br>remaining stationary before the start of the<br>competition.<br>Maximum size refers to the maximum<br>extended size of the robot moving to the<br>limit state during operation.<br>The initial size of robot ahead of the<br>competition is required to be<br>500 mm (length) x 500 mm (width) x 500<br>mm (height).<br>After intensified modification, the initial size<br>of the robot before restarting is required to<br>be 500 mm (length) x 500 mm (width) x |    |  |  |  |  |  |  |
| 2  | Weight                                                   | unlimited (height).<br>The weight of the robot must not exceed 4<br>kg. (It refers to the maximum net weight                                                                                                                                                                                                                                                                                                                                                                                                           |    |  |  |  |  |  |  |
|    |                                                          | including the weight of batteries during the competition).                                                                                                                                                                                                                                                                                                                                                                                                                                                             |    |  |  |  |  |  |  |
| 3  | Team Flag                                                | The flag surface is made of flexible material,<br>and the size shall no less than 400mm<br>(length) *300mm (width). The flag lanyard is<br>made of flexible material.                                                                                                                                                                                                                                                                                                                                                  |    |  |  |  |  |  |  |
|    |                                                          | Safety                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                                 |    |  |  |  |  |  |  |
| 4  | Dangerous Structure                                      | The robot's structure that may do harm to<br>people is required to ensure safety<br>protection during robot handling and<br>transporting.                                                                                                                                                                                                                                                                                                                                                                              |    |  |  |  |  |  |  |
| 5  | Competition Area<br>Destruction                          | Competition area destruction is prohibited in the process of robot loading, unloading and                                                                                                                                                                                                                                                                                                                                                                                                                              |    |  |  |  |  |  |  |





|    |                       | transporting.                                                                                                                                                                                                                                                                                                       |  |
|----|-----------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--|
|    |                       |                                                                                                                                                                                                                                                                                                                     |  |
| 6  | High-power Equipment  | High-power equipment is not available                                                                                                                                                                                                                                                                               |  |
|    |                       | during assembling and operating the robot.                                                                                                                                                                                                                                                                          |  |
| 7  | Unsafe Energy Storage | Please keep safe while using energy storage                                                                                                                                                                                                                                                                         |  |
|    | Equipment             | devices (spring).                                                                                                                                                                                                                                                                                                   |  |
| 8  | Personal Safety       | Contestants shall wear goggles; long hairs<br>shall be tied up; contestants are prohibited<br>from wearing toe-baring shoes to enter the                                                                                                                                                                            |  |
| 9  | Banned Material       | competition area.<br>Robots are not allowed to use the flammable<br>gases, pyrotechnic equipment, hydraulic<br>components, mercury-containing                                                                                                                                                                       |  |
|    |                       | components, exposed hazardous materials,<br>unsafe counterweights, designs that may<br>cause entanglement and competition delays,<br>sharp edges and angles, materials containing                                                                                                                                   |  |
|    |                       | liquids or gelatinous substances, and any part<br>that the electric current on the robot may be<br>conducted to the competition area.                                                                                                                                                                               |  |
|    |                       | Robot's Modules                                                                                                                                                                                                                                                                                                     |  |
| 10 | Bluetooth Controller  | Teams have to use designated controller, and it is only be used by the operator.                                                                                                                                                                                                                                    |  |
| 11 | Mainboard             | Teams have to use designated mainboard,<br>and there is only one receiving module<br>paired with controller.                                                                                                                                                                                                        |  |
| 12 | Power                 | Teams have to use batteries with specified<br>parameters as power supply to be securely<br>fixed inside the robots. Each robot can only<br>use one battery (excluding required laser<br>aiming device); Detailed parameters are: 3S<br>Li-Po batteries, output voltage: 11.1v - 11.2v,<br>discharge rate: 25c -30c. |  |
| 13 | Battery Management    | The battery management module should be                                                                                                                                                                                                                                                                             |  |
|    |                       | operated based on the requirement of                                                                                                                                                                                                                                                                                |  |

|    |                       | competition system, which must complete         |  |  |  |  |  |  |
|----|-----------------------|-------------------------------------------------|--|--|--|--|--|--|
|    |                       | three actions of power-on, power-off, and       |  |  |  |  |  |  |
|    |                       | starting the automatic program.                 |  |  |  |  |  |  |
|    |                       |                                                 |  |  |  |  |  |  |
| 14 | Self-Customized Parts | Self-customized parts can be used: plates,      |  |  |  |  |  |  |
|    | and Accessories       | profiled materials, 3D printing pieces, metals, |  |  |  |  |  |  |
|    |                       | wood, plastics, rubber, magnets; Usage          |  |  |  |  |  |  |
|    |                       | requirements for auxiliary materials: It is     |  |  |  |  |  |  |
|    |                       | allowed to use the ropes, cables, wires,        |  |  |  |  |  |  |
|    |                       | springs, rubber bands, leather hoses, surgical  |  |  |  |  |  |  |
|    |                       | tubing, punched sheets, injection molded        |  |  |  |  |  |  |
|    |                       | products; It can use commercial product         |  |  |  |  |  |  |
|    |                       | components with low integration instead of      |  |  |  |  |  |  |
|    |                       | higher integration.                             |  |  |  |  |  |  |
|    | Luminous/             | / There is no light source except the laser     |  |  |  |  |  |  |
|    | Acoustic Sensor       | sighting device and the indicator light self-   |  |  |  |  |  |  |
|    |                       | contained of the mainboard or the sensor        |  |  |  |  |  |  |
|    |                       | with its power less than 5 mW (Limited to       |  |  |  |  |  |  |
|    |                       | only one); No other sound generating device     |  |  |  |  |  |  |
|    |                       | is allowed except the buzzer on the             |  |  |  |  |  |  |
|    |                       | mainboard.                                      |  |  |  |  |  |  |
| 15 |                       | If the laser sighting device modified by the    |  |  |  |  |  |  |
|    |                       | laser pen requires independent power            |  |  |  |  |  |  |
|    |                       | supply, it can only use the configured          |  |  |  |  |  |  |
|    |                       | batteries (such as dry batteries) of the        |  |  |  |  |  |  |
|    |                       | device, and the batteries cannot transmit       |  |  |  |  |  |  |
|    |                       | energy for the robot power system. If it is not |  |  |  |  |  |  |
|    |                       | a common laser sighting device, please          |  |  |  |  |  |  |
|    |                       | provide the corresponding model and             |  |  |  |  |  |  |
|    |                       | parameters for query and verification.          |  |  |  |  |  |  |
| 16 | Servo                 | Teams have to use designated model of           |  |  |  |  |  |  |
|    |                       | smart servo (MS-12A), and the maximum           |  |  |  |  |  |  |
|    |                       | number of servo available on a robot is 6       |  |  |  |  |  |  |
|    |                       | pieces.                                         |  |  |  |  |  |  |
|    | Motor                 | The robot has to use the required DC Motor,     |  |  |  |  |  |  |
|    |                       | Encoder Motor (37 DC Motor, 180 smart           |  |  |  |  |  |  |
|    |                       | motor and the maximum number of them is         |  |  |  |  |  |  |
|    |                       | 13) to ensure the fairness of the competition.  |  |  |  |  |  |  |

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| 17 |                      | The robot shall use the required Brushless   |  |  |  |  |
|----|----------------------|----------------------------------------------|--|--|--|--|
|    |                      | Motor (2823/2824 Brushless Motor and the     |  |  |  |  |
|    |                      | maximum number of them is 2) to ensure the   |  |  |  |  |
|    |                      | fairness of the competition.                 |  |  |  |  |
| 18 | Wrap the Sharp       | The exposed sharp edges of the robots have   |  |  |  |  |
|    | Structure            | to be wrapped with sponge strips.            |  |  |  |  |
| 19 | Detachment/Shedding  | Detachment of the robot and its component    |  |  |  |  |
|    |                      | is forbidden during the competition.         |  |  |  |  |
| 20 | Interference         | It is prohibited to interfere with the       |  |  |  |  |
|    |                      | electronics and sensors of other robots.     |  |  |  |  |
| 21 | Team Number          | Team number's printing font should be        |  |  |  |  |
|    |                      | Microsoft YaHei, black bold, 130 font sizes, |  |  |  |  |
|    |                      | and the background should be in light color. |  |  |  |  |
| 22 | Engineering Notebook | Submitting project notebook containing       |  |  |  |  |
|    | Submission           | robot control source code before the         |  |  |  |  |
|    |                      | competition.                                 |  |  |  |  |
| 23 | Contaminating        | The lubricant and other materials used by    |  |  |  |  |
|    | Competition Area     | robots shall not contaminate the arena or    |  |  |  |  |
|    |                      | other robots.                                |  |  |  |  |
|    |                      |                                              |  |  |  |  |

# Appendix 4. MakeX Challenge Penalties List

| Scope     | Item           | Generation        | Violation |      |      |              | Disqualification |
|-----------|----------------|-------------------|-----------|------|------|--------------|------------------|
|           |                |                   |           | Card | Card |              |                  |
| Operation | Dangerous      | If it is found    |           |      |      | $\checkmark$ |                  |
| Rules     | Structure      | that robot's      |           |      |      |              |                  |
|           |                | structure may     |           |      |      |              |                  |
|           |                | cause damage      |           |      |      |              |                  |
|           |                | to human,         |           |      |      |              |                  |
|           |                | contestant        |           |      |      |              |                  |
|           |                | must modify it    |           |      |      |              |                  |
|           |                | after receiving   |           |      |      |              |                  |
|           |                | verbal warning.   |           |      |      |              |                  |
|           | Destruct Arena | lt will be        |           |      |      | $\checkmark$ | ~                |
|           | or Other       | disqualified if   |           |      |      |              |                  |
|           | Robots         | have a second     |           |      |      |              |                  |
|           |                | violation.        |           |      |      |              |                  |
|           |                |                   |           |      |      |              |                  |
|           | Use suspended  | If it is found    |           |      |      | $\checkmark$ | ~                |
|           | Materials      | that contestant   |           |      |      |              |                  |
|           |                | use banned        |           |      |      |              |                  |
|           |                | materials, these  |           |      |      |              |                  |
|           |                | materials will    |           |      |      |              |                  |
|           |                | be suspended.     |           |      |      |              |                  |
|           |                | A second          |           |      |      |              |                  |
|           |                | violation will be |           |      |      |              |                  |
|           |                | disqualified.     |           |      |      |              |                  |
|           | Contaminate    | Under the         |           |      |      | $\checkmark$ | ✓                |
|           | Competition    | preconditions     |           |      |      |              |                  |
|           | Area           | without           |           |      |      |              |                  |
|           |                | contaminating     |           |      |      |              |                  |
|           |                | the competition   |           |      |      |              |                  |
|           |                | area, the robots  |           |      |      |              |                  |
|           |                | can use the       |           |      |      |              |                  |
|           |                | glue, adhesive    |           |      |      |              |                  |

| MakeX Robot | ics Competition  |                              |   | K | E | Energy Innovator |
|-------------|------------------|------------------------------|---|---|---|------------------|
|             |                  | tape and<br>lubricant; These |   |   |   |                  |
|             |                  | materials will               |   |   |   |                  |
|             |                  | be suspended if              |   |   |   |                  |
|             |                  | be found, and a              |   |   |   |                  |
|             |                  | second                       |   |   |   |                  |
|             |                  | violation will be            |   |   |   |                  |
|             |                  | disqualified.                |   |   |   |                  |
|             | Robots Out of    | Any parts of                 |   |   | ~ | ✓                |
|             | Bounds           | robot are not                |   |   |   |                  |
|             |                  | allowed to go                |   |   |   |                  |
|             |                  | beyond the                   |   |   |   |                  |
|             |                  | arena                        |   |   |   |                  |
|             |                  | boundary.                    |   |   |   |                  |
|             | Other Unsafe     | The referee has              |   |   | ~ | ✓                |
|             | Factors          | the right to                 |   |   |   |                  |
|             |                  | suspend                      |   |   |   |                  |
|             |                  | contestants'                 |   |   |   |                  |
|             |                  | robot and ask                |   |   |   |                  |
|             |                  | them to                      |   |   |   |                  |
|             |                  | operate                      |   |   |   |                  |
|             |                  | modification if              |   |   |   |                  |
|             |                  | other unsafe                 |   |   |   |                  |
|             |                  | factors to be                |   |   |   |                  |
|             |                  | found. A second              |   |   |   |                  |
|             |                  | violation will be            |   |   |   |                  |
|             |                  | disqualified.                |   |   |   |                  |
| Operation   | Bring Electronic |                              | ~ | ~ |   |                  |
| Rules       | Communication    | violation will be            |   |   |   |                  |
|             | Devices          | given a yellow               |   |   |   |                  |
|             |                  | card.                        |   |   |   |                  |
|             | Delay the end    | The                          | ~ |   |   |                  |
|             | of the           | corresponding                |   |   |   |                  |
|             | competition      | score will be                |   |   |   |                  |
|             |                  | deducted.                    |   |   |   |                  |
|             | Touching in      | A yellow card                | ~ | ✓ |   |                  |
|             | Violation        | will be given if             |   |   |   |                  |

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Energy Innovator

|                   | affects the         |   |              |   |  |
|-------------------|---------------------|---|--------------|---|--|
|                   | points or the       |   |              |   |  |
|                   | progress of the     |   |              |   |  |
|                   | competition.        |   |              |   |  |
| The body is not   | A second            | ~ | $\checkmark$ |   |  |
| allowed to        | violation will be   |   |              |   |  |
| extend into the   | given a yellow      |   |              |   |  |
| arena to affect   | card.               |   |              |   |  |
| opponents'        |                     |   |              |   |  |
| score             |                     |   |              |   |  |
| Manually          | The blue-tooth      |   |              | ~ |  |
| controlling in    | controller          |   |              |   |  |
| automatic         | should be           |   |              |   |  |
| stage             | placed in the       |   |              |   |  |
|                   | storage basket      |   |              |   |  |
|                   | in automatic        |   |              |   |  |
|                   | stage.              |   |              |   |  |
| Robots' spare     | A violation will    | ~ | ~            |   |  |
| parts left in the |                     |   |              |   |  |
| arena             | on the              |   |              |   |  |
|                   | situation; A        |   |              |   |  |
|                   | yellow card will    |   |              |   |  |
|                   | be given if         |   |              |   |  |
|                   | commits a           |   |              |   |  |
|                   | second offense.     | • |              |   |  |
|                   | The scoring         | ~ |              |   |  |
| arena elements    |                     |   |              |   |  |
| from the arena    | included.           |   |              |   |  |
| Toss in           | If resulting a      |   |              |   |  |
| Violation         | change in           |   | •            |   |  |
| Violation         | opponent's          |   |              |   |  |
|                   | arena elements,     |   |              |   |  |
|                   | it should be        |   |              |   |  |
|                   | suspended for       |   |              |   |  |
|                   | restoration.        |   |              |   |  |
| Malicious         | The violators       |   |              | ~ |  |
|                   | will be given a     |   |              |   |  |
| 1                 | <b>U</b> - <i>x</i> |   |              | I |  |

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# MakeX Robotics Competition



Energy Innovator

|                  |                    | - |   | 1 1 |   |   |
|------------------|--------------------|---|---|-----|---|---|
| the opponent's   | red card.          |   |   |     |   |   |
| letter cube      |                    |   |   |     |   |   |
| Arena elements   | Repeated           |   |   |     |   | ✓ |
| are difficult to | offenses           |   |   |     |   |   |
| remove from      | affecting the      |   |   |     |   |   |
| robots           | progress of the    |   |   |     |   |   |
|                  | competition        |   |   |     |   |   |
|                  | will be            |   |   |     |   |   |
|                  | disqualified.      |   |   |     |   |   |
| Completely in    | If it fails to     |   | ~ | ~   |   |   |
| opponent's       | return to its      |   |   |     |   |   |
| camp             | own camp after     |   |   |     |   |   |
|                  | a penalty, it will |   |   |     |   |   |
|                  | be penalized by    |   |   |     |   |   |
|                  | a red card.        |   |   |     |   |   |
| Hinder           | A penalty will     | ~ | ~ | ~   | ~ | ~ |
| opponent's       | be given for       |   |   |     |   |   |
| robots           | deliberately       |   |   |     |   |   |
|                  | hindering the      |   |   |     |   |   |
|                  | opponent's         |   |   |     |   |   |
|                  | robot.             |   |   |     |   |   |
| Operating        | Please don't       | ~ | ~ | ~   | ~ | ~ |
| prohibited       | operate the        |   |   |     |   |   |
| robots           | robots that        |   |   |     |   |   |
|                  | have been          |   |   |     |   |   |
|                  | prohibited. The    |   |   |     |   |   |
|                  | violators will     |   |   |     |   |   |
|                  | receive a          |   |   |     |   |   |
|                  | violation for the  |   |   |     |   |   |
|                  | first time.        |   |   |     |   |   |
|                  | Those who          |   |   |     |   |   |
|                  | commit serious     |   |   |     |   |   |
|                  | offense will       |   |   |     |   |   |
|                  | receive a yellow   |   |   |     |   |   |
|                  | card or be         |   |   |     |   |   |
|                  | disqualified.      |   |   |     |   |   |
| Misconduct       | Misconduct is      |   |   | ~   |   |   |
| wisconduct       |                    | • | • | •   | • | • |

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| MakeX Robot  | ics Competition |                   |   | <            |   | l            | Energy Innovator |
|--------------|-----------------|-------------------|---|--------------|---|--------------|------------------|
|              |                 | including but     |   |              |   |              |                  |
|              |                 | not limited to:   |   |              |   |              |                  |
|              |                 | repeated or       |   |              |   |              |                  |
|              |                 | blatant offense;  |   |              |   |              |                  |
|              |                 | Impolite          |   |              |   |              |                  |
|              |                 | behaviors to      |   |              |   |              |                  |
|              |                 | the operators,    |   |              |   |              |                  |
|              |                 | referees, staff,  |   |              |   |              |                  |
|              |                 | or contestants;   |   |              |   |              |                  |
|              |                 | Repeated or       |   |              |   |              |                  |
|              |                 | blatant offense   |   |              |   |              |                  |
|              |                 | of safety rules;  |   |              |   |              |                  |
|              |                 | A second          |   |              |   |              |                  |
|              |                 | violation will be |   |              |   |              |                  |
|              |                 | disqualified.     |   |              |   |              |                  |
|              | Mentoring in    | A verbal          | ~ | $\checkmark$ | ~ | ~            | ~                |
|              | violation       | warning will be   |   |              |   |              |                  |
|              |                 | given for the     |   |              |   |              |                  |
|              |                 | first time.       |   |              |   |              |                  |
|              |                 | Repeated or       |   |              |   |              |                  |
|              |                 | blatant offense   |   |              |   |              |                  |
|              |                 | will be given a   |   |              |   |              |                  |
|              |                 | violation. Those  |   |              |   |              |                  |
|              |                 | who commit        |   |              |   |              |                  |
|              |                 | serious offense   |   |              |   |              |                  |
|              |                 | will be           |   |              |   |              |                  |
|              |                 | disqualified.     |   |              |   |              |                  |
|              | Contact and     | This behavior is  | ~ | $\checkmark$ | ~ | $\checkmark$ | ~                |
|              | exchange parts  | prohibited        |   |              |   |              |                  |
|              | outside the     | during the        |   |              |   |              |                  |
|              | arena           | competition.      |   |              |   |              |                  |
| Modification | Unauthorized    | Entering the      |   |              | ~ |              |                  |
| Rules        | modification    | starting area is  |   |              |   |              |                  |
|              | without         | subject to the    |   |              |   |              |                  |
|              | entering the    | direct contact    |   |              |   |              |                  |
|              | starting area   | with the line of  |   |              |   |              |                  |
|              |                 | starting area.    |   |              |   |              |                  |
|              |                 | starting area.    |   |              |   |              |                  |

| MakeX | Robotics | Competitio | Dr |
|-------|----------|------------|----|
|-------|----------|------------|----|

| Modification in  | Contestants      | ~ |   |   |   |  |
|------------------|------------------|---|---|---|---|--|
| the arena        | have to modify   |   |   |   |   |  |
|                  | the robot        |   |   |   |   |  |
|                  | outside the      |   |   |   |   |  |
|                  | arena.           |   |   |   |   |  |
| Initiatively     | The              | > | ~ |   |   |  |
| change the       | competition      |   |   |   |   |  |
| arena elements   | elements         |   |   |   |   |  |
| in modification  | removed from     |   |   |   |   |  |
| stage            | the robots       |   |   |   |   |  |
|                  | should be        |   |   |   |   |  |
|                  | placed in the    |   |   |   |   |  |
|                  | arena, which     |   |   |   |   |  |
|                  | will not change  |   |   |   |   |  |
|                  | the state of     |   |   |   |   |  |
|                  | other elements.  |   |   |   |   |  |
|                  |                  |   |   |   |   |  |
| Failure to enter | Robots can't     |   |   |   | ~ |  |
| the arena        | enter the arena  |   |   |   |   |  |
| before the end   | anymore.         |   |   |   |   |  |
| of the           |                  |   |   |   |   |  |
| modification     |                  |   |   |   |   |  |
| stage            |                  |   |   |   |   |  |
| Bring            | Robots carrying  |   |   |   | ✓ |  |
| competition      | competition      |   |   |   |   |  |
| elements into    | elements are     |   |   |   |   |  |
|                  | not allowed to   |   |   |   |   |  |
| modification     | enter the        |   |   |   |   |  |
|                  | arena.           |   |   |   |   |  |
| Incompatible     | If there are any |   |   | ~ | ~ |  |
| the state of     | major changes,   |   |   |   |   |  |
| inspection after | the contestants  |   |   |   |   |  |
| modification     | should declare   |   |   |   |   |  |
|                  | to the referees  |   |   |   |   |  |
|                  | for inspection   |   |   |   |   |  |
|                  | after robots are |   |   |   |   |  |
|                  | put into the     |   |   | 1 |   |  |

| MakeX Rob | otics Competition |                   | < | l | Energy Innovat | or |
|-----------|-------------------|-------------------|---|---|----------------|----|
| Identical | The               | It is not allowed |   |   | ~              |    |
| Robot     | appearance of     | for two or more   |   |   |                |    |
|           | identical robot   | than two robots   |   |   |                |    |
|           |                   | with high         |   |   |                |    |
|           |                   | degree of         |   |   |                |    |
|           |                   | similarity to     |   |   |                |    |
|           |                   | participate in    |   |   |                |    |
|           |                   | the               |   |   |                |    |
|           |                   | competition. If   |   |   |                |    |
|           |                   | such situation    |   |   |                |    |
|           |                   | occurs during     |   |   |                |    |
|           |                   | the inspection,   |   |   |                |    |
|           |                   | it will be        |   |   |                |    |
|           |                   | determined by     |   |   |                |    |
|           |                   | judge group       |   |   |                |    |
|           |                   | leader.           |   |   |                |    |



# **Appendix 5 MakeX Challenge Score Sheet**

|                                                     | <b>A</b><br>22 Mak |                            | ROBC                                               |           | OMPETITION                                         |               |  |
|-----------------------------------------------------|--------------------|----------------------------|----------------------------------------------------|-----------|----------------------------------------------------|---------------|--|
| Competitio                                          | on Info: Qu        | alificati                  | on Round 🔲 / Eliminatio                            |           | (Arena) No                                         | _ (Session)   |  |
| Registration                                        |                    |                            | Match Points                                       | i         |                                                    | Winner        |  |
| Red Alliance                                        | Red Alliance       |                            |                                                    | Blue A    | Alliance                                           |               |  |
| Red Amance                                          | (25 points each)   |                            | Pin                                                |           | (25 points each)                                   |               |  |
| Feam 1 (No.) :                                      | (20 point          | ts each)                   | Recovering New E                                   | nergy Pin | (20 points each)                                   | Red Alliance  |  |
| Feam 2 (No.) :                                      | (15 point          | nts each) Computing Data C |                                                    | ube       | (15 points each)                                   |               |  |
|                                                     | (30 points each)   |                            | Storaging Data Cube                                |           | (30 points each)                                   |               |  |
| Blue Alliance                                       | (5 points each)    |                            | Scrambling Data Cube                               |           | (5 points each)                                    |               |  |
|                                                     | (50 points each)   |                            | Flag                                               |           | (50 points each)                                   |               |  |
| Feam 1 (No.) :                                      | 150 points         |                            | MakeX Bonus                                        |           | 150 points                                         | Blue Alliance |  |
| Feam 2 (No.) :                                      |                    |                            | Penalty                                            |           |                                                    |               |  |
|                                                     |                    |                            | Total Points                                       |           |                                                    |               |  |
| Captain of Red Alliance:                            |                    | Ca                         | ptain of Blue Alliance:                            |           | Remark                                             |               |  |
| (Please confirm the scoring results and sign here ) |                    |                            | Please confirm the scoring<br>ults and sign here ) |           |                                                    |               |  |
| Referee of Red Alliance:                            |                    | Ret                        | Referee of Blue Alliance:                          |           | e's any disagreement al<br>down the situation clea |               |  |
| (Please confirm the scoring results and sign here ) |                    |                            | lease confirm the scoring<br>ults and sign here )  |           |                                                    |               |  |



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# **Appendix 6 Instructions for Li-Po Battery**

To ensure the safety of Li-Po battery, each team should designate a person to supervise the usage of battery, and to inform the teammates about the safety instructions for Li-Po battery. The following issues should be noted while using Li-Po battery:

- Please use the Li-Po battery while ensuring that you carefully read and understand the safety instructions.
- Safely charging and discharging.
- It is required to use the specified charger for Li-Po battery provided by the manufacturer, as well as read the instructions for charger carefully. In case of emergencies to be dealt with, please ensure that someone is nearby during charging. Please do not overcharge or over-discharge. It will be deemed overcharge if the voltage of a single battery cell is over 4.2v, and less than 3.0v is over-discharge. Overcharge may cause the explosion of the Li-Po battery, while over-discharge can easily damage the battery and shorten the service life of it.
- Please check the battery's voltage and electricity quantity carefully before charging or using.
- Please charge the battery at 0-45  $^{\circ}$ C.
- Safe storage
- The battery cell cannot be overheated any time. When the temperature of the battery cell is as high as 60°C, there will be potential safety hazards, even burning.
- In the process of charging, the battery is not required to be closely or placed directly on flammable materials (paper, plastic, etc.). If conditions permit, it is best to charge it in a fire-proof safe box.
- Please do not put batteries near liquids, open fire or heaters. Place batteries out of reach by kids.
- Please do not detach and restructure the batteries arbitrarily or change its wiring, do not assemble the batteries privately. The following behaviors are

deemed as dangerous: detach and restructure the old battery cells, or restructure one of the detached battery cells with another restructured one (It can easily cause short-circuit combustion without the particular assembly instrument).

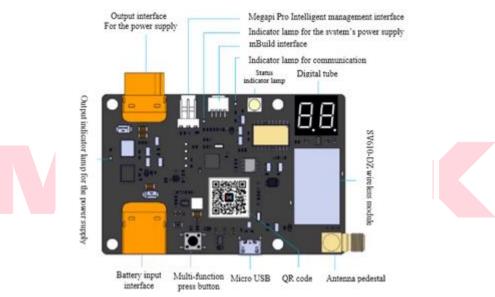
- If occurs collision during the competition, please take out the battery. Please carefully check the state of battery and connector. (Note: Batteries may be overheated with high temperature.)
- Do not spill electrolyte on eyes or skin. In case it spills inadvertently, please wash it with clean water immediately. In case it is serious, please seek medical care immediately.
- No short circuit is allowed (positive and negative poles are connected).
- Do not directly contact the leaked battery.
- For batteries that are not used for a long time, please ensure a charge-discharge activation within 3 months to maintain the stability.
- During the storage and transportation of Li-Po batteries, please place them in the special fire-proof safety bags or safety boxes.

# **Appendix 7 Power Management Module**

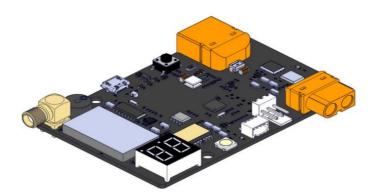
#### Introduction of Power Management Module

The power management module is used in coordination with the main board (NovaPi), which is a necessary electronic device to participate in the competitions of 2021 Season energy innovator and ultimate warrior.

During the competition, the power management module is wirelessly connected with the MakeX competition system, so that the MakeX competition system can control the power supply of the teams' robots, as well as switch between automatic and manual programs.



Module Size: 85mm(length) x 56mm(width) x 11.5mm(height);



Working Voltage: 6V - 12V;

#### **On-board LED Lamp**

LED Lamp includes an indicator lamp for power output, an indicator lamp for system

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power and an indicator lamp for communication

• Indicator Lamp for Power Output: The red indicator lamp is always on when having power output, and goes off when the power is disconnected.

• Indicator Lamp for System Power: The red indicator lamp for system power is always on when the module is working.

• Indicator Lamp for Communication: The blue indicator for lamp communication flashes when the module updates its firmware.

## Indicator Lamp for Status (RGB Lamp)

• Indicator lamp for status mainly includes four statuses: power off, red, green and blue.

• **Power Off:** The blue-tooth module is detected after the power management module is powered on. The RGB lamp is powered off when the blue-tooth module cannot be detected.

- Red: After a normal power-on, click the button and the RGB lamp flashes red once;
- Green: In manual stage;
- Blue: In automatic stage.

#### **Digital Tube**

The two-digit digital tube is mainly used to display the current channel and an abnormal state of the wireless communication module.

 In the normal state, the channel number of the current wireless communication module is displayed by the two-digit digital tube. The channel number of the wireless communication module is 1~40, so that the number displayed by the digital tube is 1~40. If the current channel is 16 channels, the two-digit digital tube displays the number "16".

• The power management module will detect the wireless communication module when it is powered on. If the wireless communication module cannot be detected, the 2-digit digital tube will display the letter "Er", meaning error.

• When the battery is low powered, the two-digit digital tube displays the symbol "-" and the current channel number alternately.





#### Buzzer

The buzzer will send the sounds of reminding and warning.

• The buzzer will shortly buzz when the module is normally powered on and be detected, together with the wireless communication module is online;

• When the power management module is reset, the buzzer will sound for 2 seconds;

• When the wireless communication module cannot be detected after power-on, the buzzer rings three times continuously.

# **Operation of Power Management Module**

## Multi-function Button

Multifunctional button has four modes: reset, click, double-click and long-press.

• **Reset:** Firstly, press the multi-function button and meanwhile insert the Li-Po battery into the power management module. The power management module restores the default configuration parameters. The buzzer sounds for 2 seconds and the digital tube displays the number "20";

• Click: Click the multi-function button once, the power management module reports the blue-tooth module UID once, and the RGB lamp flashes red once.

• **Double Click**: Double click the multi-function button once, the power management module will delay 3 seconds and switch between the automatic program and manual program (It can be observed whether the state switch is successful through the RGB indicator, the RGB blue lamp is always on during automatic stage, the RGB green lamp is always on during manual stage, and the RGB lamp flashes during the delayed switching). Double click is only valid when the blue-tooth module is the defaulted to "20" channel (It is only valid when the digital tube displays the number "20");

• Long Press: Long press the multi-function button (2-3 sec.) to switch the output state of the power supply. That is if the current power is disconnected, the power will connect after long pressing and its indicator lamp becomes red. If the power connects, the power will disconnect after long pressing and its indicator lamp powers off.



## Starting Signal Identification Code of Automatic Program

• In automatic stage, the competition system sends relevant instructions to the power management module of the robot, so as to shield the controller signal and start the automatic program of the robot. In order to start the automatic program on the mainboard normally, it is necessary to insert a fixed code into the program to identify the instructions to start the automatic program sent by the competition system.

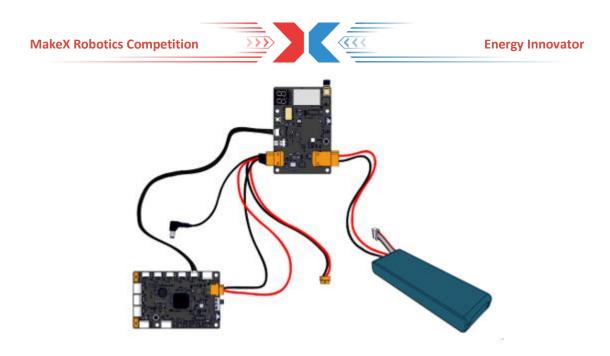
| NovaPi Main Program                                                     | define Manual procedure                    |
|-------------------------------------------------------------------------|--------------------------------------------|
| forever                                                                 | K encoder motor M1 ▼ rotates at power 50 % |
| if Competition is in Automatic Stage? then<br>Automatic program<br>else | define Automatic program                   |
| Manual procedure                                                        | K encoder motor M2 ▼ rotates at power 50 % |
|                                                                         | CE X                                       |

(Please put the program in manual stage and automatic stage into the corresponding positions.)

# Installation Manual

• The power management module is a necessary electronic component for the competition. Please make sure that it is securely fixed, and cables are tightly connected. For protection, it is suggested to use an acrylic box of power management module;

• The data cables leading to the mainboard must be connected firmly as follows:



 Adjust the position of the antenna to prevent it from interfering with the movement of other motion devices, and try to avoid the antenna exposed to metal materials;

• The power management module must be fixed on the surface of the robot and be accessible to scan (power management module ID);

• The following operations are not allowed at any stage after the start of the competition, especially during the modification stage:

1. The replacement of Li-Po battery or re-unplugging and re-plugging of the Li-Po battery.

2. Press the reset button of the power management module (any operation of the power management module is prohibited).

• When the competition is finished, the robot needs to be re-powered by itself, and the power supply can be restored by unplugging and plugging the Li-Po battery;

• The power management module corresponds to the teams' information in the competition system one by one. Please do not replace that module without authorization. If it needs to be replaced, please contact the staff. Any problems caused by the unauthorized replacement of the power module shall be borne by the team.

•

# **Appendix 8 Supplementary Explanation of Competition Procedure**

Explanation of Recommended Procedure

## **Engineering Notebook Submission**

MakeX Robotics Competition Committee encourages teams to record engineering notes, and excellent notes will be an important basis for team's award evaluation. The submission of paper engineering notebook and award setting based on prematch notice and program brochure. Generally speaking, the submission of paper engineering notes is a necessary in medium and large-scale events, which will serve as an important basis for the award evaluation. Please refer to **Appendix 2** 

## Engineering Notebook Guideline.

## **Pits Area Decoration**

Each team has its own space in the pits area, where teams can decorate their space to make their teams known to people, and participate in the award evaluation. Teams can rest and debug robots in the pits area, and please keep the area clean and tidy. The suggestions are as follows:

1. Display Content (provided by teams)

Team Flag

HD Images (3-4 copies)

Team Introduction (no more than 200 words)

Peripheral Display (if any)

2. Display Form

Team Poster/Roll Up Banner + Team Flag + Team Peripheral (if any) + Team Members/Teachers' Onsite Suggestion

# **Practice Round**

Teams who have finished their robot inspection can participate in practice round. The schedule will be announced at the entrance in form of notices, and teams are required to queue in line before entrance. Not all competitions have a practice round, which can be informed based on actual situation.

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#### **Team Assessment**

MakeX encourages contestants to master theoretical knowledge of robots as well as develop their creativity and skills of making robots by participating in the competition. By the method of Q&A and onsite problem-solving, the assessment with 10 minutes will be conducted to examine students' knowledge of robots. In this procedure, all team members must participate together except their mentors. Each team should attend the assessment on time, with 1 copy of the engineering notebook and the robot.

The assessment, with its aim to examine students' knowledge of robot, will be conducted in three aspects, including basic robotics theory, machinery and programming as well as innovation. The judges will ask questions or require an onsite operation demonstration. In a regular points race, teams can obtain different score (5, 3, 2, 0) based on their onsite performance grade (S, A, B, C). The assessment result will be announced on the MakeX official website after the qualification round. Teams obtaining zero point in the assessment procedure will not be able to enter the elimination round. The assessment score will be adjusted accordingly for different grade of point races.

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# **Appendix 9 Competition Resources**

Competition resources include but are not limited to official resources provided by the committee, such as Competition Guide, Equipment Instructions, Rules Videos, etc. The contestants are obliged to keep abreast of the update of competition resources before the competition, and any problems caused by the players' failure to keep abreast of the updates shall be borne by the players themselves. All official competition resources will be updated on MakeX Website

# https://www.makex.cc/en.

MakeX Robotics Competition Committee will revise and improve the Rules Guide with the progress of the competition and the new version will be announced in MakeX Official Website https://www.makex.cc/en. The contestants and mentors can download the latest version in MakeX

Website Download https://www.makex.cc/en/information/download. MakeX Official Website: https://www.makex.cc/en.

Any Feedback & Question Please Sent to: makex\_overseas@makeblock.com

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